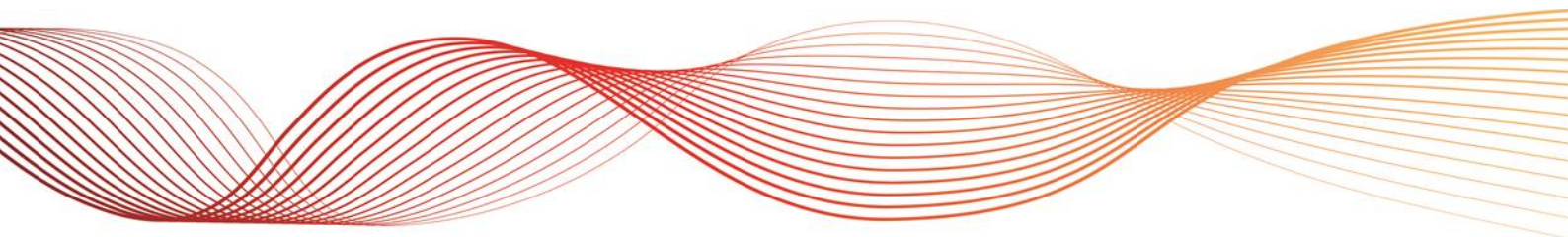




# MULTIPLE VOLTAGE DISTURBANCE RIDE-THROUGH CAPABILITY

JUSTIFICATION OF AEMO'S PROPOSAL

**March 2018**





# IMPORTANT NOTICE

## Purpose

AEMO has prepared this document to provide information about multiple-fault ride-through performance requirements of generators, as at the date of publication.

## Disclaimer

This document or the information in it may be subsequently updated or amended. This document does not constitute legal or business advice, and should not be relied on as a substitute for obtaining detailed advice about the National Electricity Law, the National Electricity Rules, or any other applicable laws, procedures or policies. AEMO has made every effort to ensure the quality of the information in this document but cannot guarantee its accuracy or completeness.

Accordingly, to the maximum extent permitted by law, AEMO and its officers, employees and consultants involved in the preparation of this document:

- make no representation or warranty, express or implied, as to the currency, accuracy, reliability or completeness of the information in this document; and
- are not liable (whether by reason of negligence or otherwise) for any statements or representations in this document, or any omissions from it, or for any use or reliance on the information in it.

## Copyright

© 2018 Australian Energy Market Operator Limited. The material in this publication may be used in accordance with the [copyright permissions](#) on AEMO's website.



## EXECUTIVE SUMMARY

AEMO has proposed new requirements (access standards) for all types of generation to ride through multiple disturbances (faults) as part of its proposed rule change on generator technical performance standards. These new access standards aim to balance power system security requirements and maintenance of plant integrity.

The criteria forming the basis of an assessment against the proposed access standards were:

- The total number of disturbances within pre-defined sliding time windows ( $N_F$ );
- The accumulated disturbance duration ( $\Delta t$ ); and
- The sum of changes in voltage by the duration of the disturbance ( $\Delta V \times \Delta t$ ).

A detailed description of how these criteria are to be assessed is provided in Section 3.

Power system modelling and analysis demonstrated that the proposed access standards can be met by a range of new and existing synchronous and asynchronous generation.

The simulation results showed a range of OEM technologies can ride through the required number of disturbances ( $N_F$ ).  $\Delta t$  and  $\Delta V \times \Delta t$  are calculated for each case, where the proposed  $\Delta t$  criterion is met in some cases, and the proposed  $\Delta V \times \Delta t$  criterion is met for long, shallow disturbances.

These results showed the proposed access standards are practical and achievable.

Where a generating system failed to ride through multiple disturbances simulation results showed that the disturbance sequence exceeded the requirements of the proposed access standards.

These results showed the proposed access standards have fully considered the limitations of the power system and the generating system. AEMO, therefore, proposes that a generating system is not required to ride through a combination of disturbances if it leads to one proposed criterion being exceeded.

The simulation studies presented in this document have provided sufficient evidence to demonstrate the proposed access standards strike a balance between power system security and generating system safety, and can be met by various generation technologies.

# GLOSSARY

The acronyms, symbols and abbreviations in Table 1 have the meanings set out opposite them when used in this document.

**Table 1 Defined terms**

Symbol	Definition
#p	#-phase fault, i.e. 1p = one phase, 2p = two phase, 3p = three phase
dT	See $\Delta t$
dV	See $\Delta V$
dV x dT	See $\Delta V \times \Delta t$
N <sub>F</sub>	Total number of disturbances
$\Delta V_N $	Voltage drop at the connection point, referenced from 90% of the normal voltage
$\Delta t$	Accumulated disturbance duration (Change in time)
$\Delta V$	Change in voltage
$\Delta V \times \Delta t$	Sum of changes in voltage by the duration of the disturbance
Acronym	Definition
AEMO	Australian Energy Market Operator
DEG	Degrees
DNSP	Distribution Network Service Provider
GPS	Generator Performance Standards
kV	Kilo-Volt
LVRT	Low Voltage Ride-Through
ms	milliseconds
MVA	Mega Volt Ampere
MW	Megawatt
NEM	National Electricity Market
NER	National Electricity Rules
NSP	Network Service Provider
OEM	Original Equipment Manufacturer
PSCAD™/EMTDC™	Power System Computer Aided Design / Electromagnetic Transient with Direct Current
PSS®E	Power System Simulator for Engineering
pu	per unit
pu.s	Per-unit Seconds
QLD	Queensland
RMS	Root Mean Square
s	seconds
SA	South Australia
SCR	Short Circuit Ratio
SMIB	Single Machine Infinite Bus
WSCR	Weighted Short Circuit Ratio



# CONTENTS

<b>EXECUTIVE SUMMARY</b>	<b>1</b>
<b>GLOSSARY</b>	<b>2</b>
<b>PROPOSED STANDARD</b>	<b>5</b>
1. <b>PURPOSE</b>	<b>8</b>
2. <b>THE NEED TO RIDE THROUGH MULTIPLE FAULTS</b>	<b>8</b>
3. <b>ASSESSMENT CRITERIA</b>	<b>9</b>
4. <b>APPLICATION OF PROPOSED REQUIREMENTS DURING GPS NEGOTIATION STAGE</b>	<b>11</b>
5. <b>SIMULATION CASE STUDIES TO SUPPORT THE PROPOSED REQUIREMENTS</b>	<b>11</b>
6. <b>CONCLUSION</b>	<b>16</b>
<b>APPENDIX A. PSS®E SIMULATION RESULTS</b>	<b>18</b>
<b>APPENDIX B. CONTROL SYSTEM INTERACTION AND LOW VOLTAGE RIDE-THROUGH RE-TRIGGERING</b>	<b>37</b>
<b>APPENDIX C. DETAILED DEFINITIONS</b>	<b>42</b>
C.1 Sliding window reset time	42
C.2 Considered disturbances	43
C.3 Deep disturbance (fault) threshold	44
<b>APPENDIX D. PSCAD™/EMTDC™ SIMULATION RESULTS FOR SYNCHRONOUS GENERATING UNITS AUXILIARY SUPPLIES</b>	<b>45</b>
<b>APPENDIX E. COMPARISON OF PSCAD™/EMTDC™ AND PSS®E MODEL PERFORMANCE FOR MULTIPLE DISTURBANCE RIDE THROUGH</b>	<b>47</b>

# TABLES

Table 1	Defined terms	2
Table 2	Proposed access standards for multiple-disturbance ride-through requirement	5
Table 3	Definitions of terms used in the proposed access standards	7
Table 4	Generating systems investigated in the assessment	12
Table 5	Simulation results for generation successfully riding through multiple disturbances	13
Table 6	Simulation results of generator failing to ride through multiple disturbances	15

# FIGURES

Figure 1	Example disturbance sequence with long fault duration	7
Figure 2	South Australian power system faults per period	8



Figure 3	Queensland power system faults per period	9
Figure 4	Calculation of $\Delta V \times \Delta t$	10
Figure 5	Case 1a-1 Synchronous Generating System 1 Stable Case 1	18
Figure 6	Case 1a-2 Synchronous Generating System 1 Stable Case 2	19
Figure 7	Case 1a-3 Synchronous Generating System 1 Stable Case 3	20
Figure 8	Case 2-1 Synchronous Generating System 2 stable Case 1	21
Figure 9	Case 2-2 Synchronous Generating System 2 stable Case 2	22
Figure 10	Case 2-3 Synchronous Generating System 2 stable Case 3	23
Figure 11	Case 3-1 Asynchronous Generating System 1 stable Case 1	24
Figure 12	Case 3-2 Asynchronous Generating System 1 stable Case 2	25
Figure 13	Case 3-3 Asynchronous Generating System 1 stable Case 3	26
Figure 14	Case 4-1 Asynchronous Generating System 2 stable Case 1	27
Figure 15	Case 4-2 Asynchronous Generating System 2 stable Case 2	28
Figure 16	Case 4-3 Asynchronous Generating System 2 Stable Case 3	29
Figure 17	Case 5-1 Asynchronous Generating System 3 Stable Case 1	30
Figure 18	Case 5-2 Asynchronous Generating System 3 Stable Case 2	31
Figure 19	Case 5-3 Asynchronous Generating System 3 Stable Case 3	32
Figure 20	Case 6-1 Asynchronous Generating System 4 Stable Case	33
Figure 21	Case 1b-1 Synchronous Generating System 1 unstable Case 1	34
Figure 22	Case 1b-2 Synchronous Generating System 1 unstable Case 2	35
Figure 23	Case 1b-3 Synchronous Generating System 1 unstable Case 3	36
Figure 24	Connection point voltage drops to 85%, no LVRT re-triggering	38
Figure 25	Connection point voltage drops to 80%, LVRT re-triggering	39
Figure 26	Connection point voltage drops to 75%, LVRT re-triggering	40
Figure 27	Connection point voltage drops to 70%, no LVRT re-triggering	41
Figure 28	Concept of sliding window	42
Figure 29	Example of disturbance sequence for the proposed automatic access standard	43
Figure 30	Example of disturbance sequence for the proposed minimum access standard	43
Figure 31	Fault voltage – Phase RMS voltage	44
Figure 32	Fault voltage – Positive sequence voltage	44
Figure 33	Auxiliary supplies terminal voltages	45
Figure 34	Auxiliary supplies performance – motor speed	45
Figure 35	Auxiliary supplies performance – motor torque	46
Figure 36	Wind farm active power comparison between PSCAD™/EMTDC™ and PSS®E models	47
Figure 37	Wind farm reactive power comparison between PSCAD™/EMTDC™ and PSS®E models	47



# PROPOSED STANDARD

The proposed multiple-disturbance ride-through requirement is summarised in Table 2, with specific terminology definitions in Table 3.

**Table 2 Proposed access standards for multiple-disturbance ride-through requirement**

Elements	Automatic access standards	Minimum access standards
Total no. of disturbances	15	6
Sliding window reset time	5 minutes	30 minutes <sup>A</sup>
Accumulated disturbance duration (millisecond) <sup>B</sup>	1800	1000
Sum of $\Delta V \times \Delta t$ (pu.second)	1.0	0.5 <sup>C</sup>
Number of deep disturbances (connection point voltage during disturbance < 50%)	6	3
Minimum time difference between successive disturbances	No minimum <sup>D</sup>	200 ms
Type of disturbances to be considered <sup>E</sup>	<ul style="list-style-type: none"> <li>One disturbance cleared by breaker-fail protection system</li> <li>One long-duration shallow disturbance, e.g. 80% residual voltage for 2 s as per clause S5.2.5.4</li> <li>One deep three-phase disturbance (or two deep three-phase disturbances in parts of network where a three-phase auto-reclosing is permitted)</li> <li>Remaining disturbances are unbalanced</li> <li>An unsuccessful auto-reclosure is counted as two disturbances</li> </ul>	<ul style="list-style-type: none"> <li>One disturbance cleared by breaker-fail protection system</li> <li>One long-duration shallow disturbance, e.g. 80% residual voltage for 2 s as per clause S5.2.5.4</li> <li>All disturbances are unbalanced</li> <li>An unsuccessful auto-reclosure is counted as two disturbances</li> </ul>

A. This means that the generating system must withstand the same number of voltage disturbances within a five-minute interval. However, no further ride-through capability is required until the 30-minute interval expires. For further details see Appendix C.1.

B. These requirements are applied in addition to the NER clause S5.2.5.4 requirements.

C. Any non-credible contingency, or any individual contingency causing a synchronous generating system to exceed its critical fault clearance time is excluded from assessment of the proposed access standard.

D. Meaning that two successive disturbances can occur one after another with practically zero time difference. However, it is recognised that in reality not all 15 faults will occur with 0 ms separation in between. Randomly distributed time differences between successive disturbances, ranging from 0 to 200 ms, may be applied by the Applicant. The sequence studied should include at least two pairs of successive disturbances with 0 ms time difference in between.

E. Disturbances should not result in the generating system under consideration being islanded, or cause large sections of the transmission or distribution network being lost.

## Time between disturbances

The proposed automatic access standard does not specify any value or range of values for the minimum time difference between successive disturbances, because it is not possible to control or anticipate the next disturbance due to its inherent randomness. Any two successive disturbances could be zero seconds apart. Assessment should, therefore, be made on this basis, with intervals between fault clearance and inception as low as zero seconds provided that the power system to which the generating system is connected remains stable. The proposed minimum access standard allows for a 200 ms time difference between the clearance of a preceding disturbance and the occurrence of the succeeding disturbance.

## Applicable access standards versus generating technologies

Synchronous machines are directly coupled to the power system and their primary components are, therefore, exposed to various impacts of disturbances, including thermal, mechanical, and electrical adverse impacts.

Asynchronous generating systems generally have components that are more susceptible to disturbances fully or partially decoupled from the power system disturbance with their fast control systems further minimising the impact of disturbances.

Given these inherent technology differentiators, it is proposed that an acceptable performance standard for asynchronous generating systems should be at, or as close as possible to, the proposed automatic access standard, whereas a wider range of negotiated outcomes may be acceptable for synchronous machines considering the key technological differentiators discussed above.

### **Diversity in physical locations and severity of disturbances**

The proposed access standards acknowledge that the occurrence of a large number of deep voltage disturbances in close proximity to a generating system could result in the generating system being islanded and inoperable, or large sections of adjacent transmission or distribution network being out of service. The proposed access standards specify the maximum number of deep disturbances (with a connection point voltage of less than 50%) that needs to be considered, with the remaining shallower disturbances resulting in a residual voltage of greater than 50%. For each connection, the selection of the number of deep and shallow disturbances must consider the characteristics of the surrounding power system, thereby applying the disturbances at a wide variety of physical locations not to cause the generating system being islanded.

### **Fault type and duration**

Applicants must only apply the disturbances listed in “Type of disturbances to be considered” in Table 2 to assess whether they can meet the proposed generator performance standards with respect to multiple voltage disturbances.

The fault clearance time for each fault in isolation must be within the relevant primary protection or circuit breaker failure clearance time for the specific faults appropriate to the generating system under consideration, and as specified in the generator performance standards for that facility.

The fault clearance times applied to synchronous machines for this assessment must be below the respective critical clearing time. Longer duration faults must not be applied.

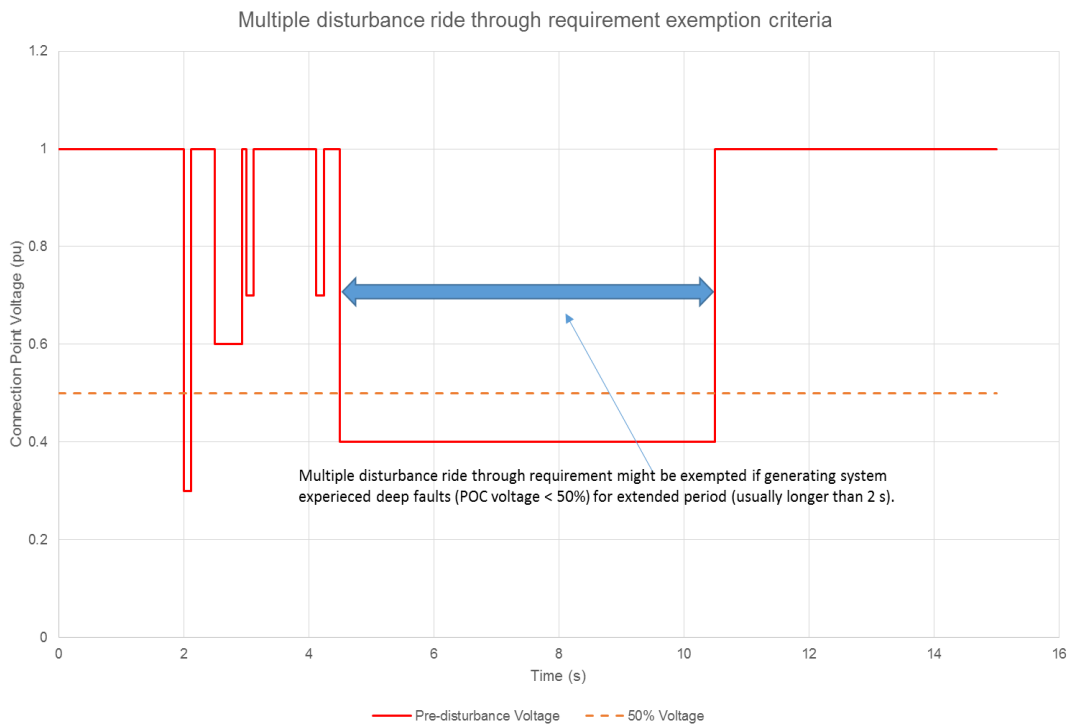
Some generating systems connected to remote distribution systems can be subject to deep faults with fault clearance times in the order of several seconds with possible auto-reclosure. Such long duration disturbances are outside the scope of the proposed access standards, as these types of disturbances affect a very limited part of the network. Therefore, an inability to ride through a number of such disturbances will have a limited impact on power system security. In recognition of this limitation, and that a 1-second clearance time for a deep fault would exceed the minimum access standard  $Sum\ of\ \Delta V \times \Delta t$  criteria, the maximum fault duration to be applied in multiple fault ride-through assessments should not exceed 1 s.

An example of such a disturbance sequence is illustrated in Figure 1.

Note that assessment against single contingency and reclose events for the purposes of assessing whether the requirement in NER clause S5.2.5.5 can be met must still occur considering the actual clearance times for long duration disturbances.



**Figure 1 Example disturbance sequence with long fault duration**



In the above example, the generating system had successfully ridden through the first four disturbances. The fifth disturbance caused the connection point voltage to drop below 50% for five seconds. The generating system is not, therefore, required to ride through the fifth long duration disturbance.

### Definitions

The following table provides the meanings of certain terms used in the proposed access standards.

**Table 3 Definitions of terms used in the proposed access standards**

Term	Definition
<b>Accumulated disturbance duration (<math>\Delta t</math>)</b>	The total time in which the connection point voltage is below the lower nominal operating band of 0.9 per unit. More details in Section 3.1.1.
<b>Deep disturbance</b>	When the connection point voltage is below 50%. This is generally the lowest of the three-phase voltages. When a fault ride-through strategy uses the positive-sequence voltage for initiating the ride-through sequence, the positive-sequence voltage will be used for assessing the number of deep voltage disturbances in Table 2. More details in Appendix C.3.
<b>Sliding window reset time</b>	The total time from the first disturbance in a sequence of disturbances (as per Table 2) that must expire before a generating system is required to withstand further faults. More details in Appendix C.1.
<b>Sum of <math>\Delta V \times \Delta t</math> (<math>\Delta V \times \Delta t</math>)</b>	The time integral of the connection point voltage and 0.9 per unit, when the voltage is below 0.9 per unit. More details in Section 3.1.3.

# 1. PURPOSE

This report provides supporting evidence on the suitability of the proposed access standards for multiple voltage disturbances in quick succession, with simulation results confirming that the proposed range of access standards are practical, and can be met by various generation technologies.

# 2. THE NEED TO RIDE THROUGH MULTIPLE FAULTS

To determine the number of voltage disturbances for the proposed automatic and minimum access standards, fault records from the South Australian (SA) and Queensland (QLD) power systems were analysed to determine the maximum historical number of faults within pre-defined time windows.

Figure 2 shows the maximum number of historical faults for a 10-year period between 2006 and 2016 (including the black system event) for the SA transmission and distribution network (66 kV only). Where a fault occurred in the Victorian transmission network but was reflected into part of the SA transmission and distribution network, this was not considered as an SA network fault in this figure. In practice, some of these faults, especially those at or near the Heywood Interconnector, will also be seen as a fault by some of the generating systems in SA. This results in a further increase in the total number of faults seen by SA generating systems compared to considering faults originating from within the SA network only.

**Figure 2 South Australian power system faults per period**

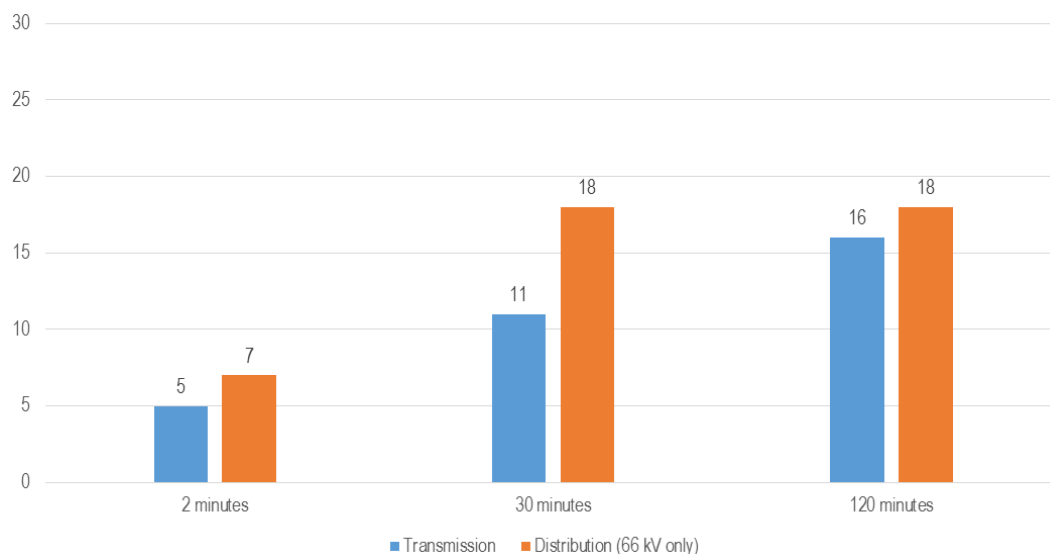
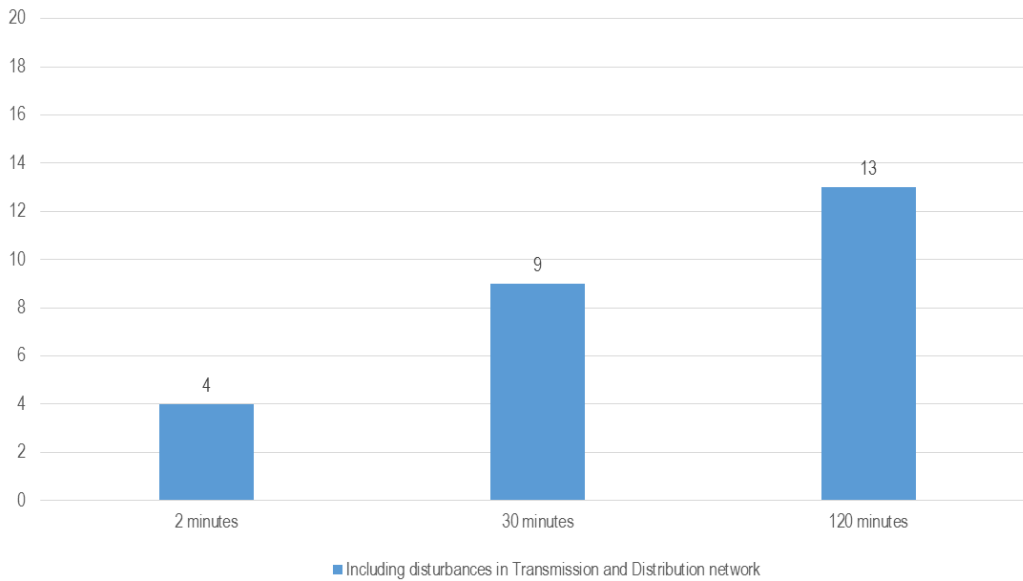


Figure 3 shows the maximum number of historical faults for a 10-year period between 2007 and 2017 (including when Cyclone Yasi hit Queensland) for the Queensland transmission and distribution networks. This data includes all events that resulted in a Powerlink item of plant being unexpectedly removed from service, and events where third party equipment (DNSP or Generator) had tripped but also impacted Powerlink’s plant.

**Figure 3 Queensland power system faults per period**



It should be noted the historical fault data in Queensland does not consider an auto-reclosing event as a second disturbance, whereas SA’s historical fault data does.

The data shows that a large number of voltage disturbances in quick succession occurred in the past and can occur in multiple regions. It is, therefore, expected that all types of generation technologies should support power system security by being able to withstand a sufficient number of voltage disturbances of various types and duration without disconnection, or ceasing to inject active and reactive currents during and after each disturbance.

### 3. ASSESSMENT CRITERIA

The inability of generation to withstand multiple faults in quick succession could result from electrical, mechanical, or thermal limitations (or failures) of primary plant components, or settings of control and protection systems. This can, in turn, trigger a rapid cessation of energy generation.

The limitations are generally an accumulation of the effect of each individual disturbance on the generating systems. The sudden loss of numerous generating facilities across the network leads to potential risk of cascaded failure across parts of the power system.

Recognising this, and the need to strike a balance between power system security and maintaining plant integrity due to multiple voltage disturbances in quick succession, the following assessment criteria for determining whether a proposed generating system can meet the multiple-fault ride-through access standards are proposed:

- a) An accumulated disturbance duration ( $\Delta t$ ).
- b) A total number of disturbances within pre-defined sliding time windows ( $N_F$ ).
- c) Sum of changes in voltage by the duration of the disturbance ( $\Delta V \times \Delta t$ ).

AEMO will be satisfied that a generating system can meet the proposed access standards when at least one of these criteria is met.

In proposing these criteria, AEMO has taken into consideration the physical and design limits of various generation technologies, and the types of disturbances (by reference to severity and accumulated

duration) a generating system must ride through to maintain power system security in a practical Australian environment<sup>1</sup>.

More information about how each of the criteria is to be assessed is in the following sections.

### 3.1.1 Accumulated disturbance duration ( $\Delta t$ )

This is the cumulative amount of time where the connection point voltage is below 90% of the normal voltage ( $\Delta|V_N| > 0.1$  per unit [pu]), where  $\Delta|V_N|$  is defined as the voltage *drop* at the connection point from 90% of the normal voltage.

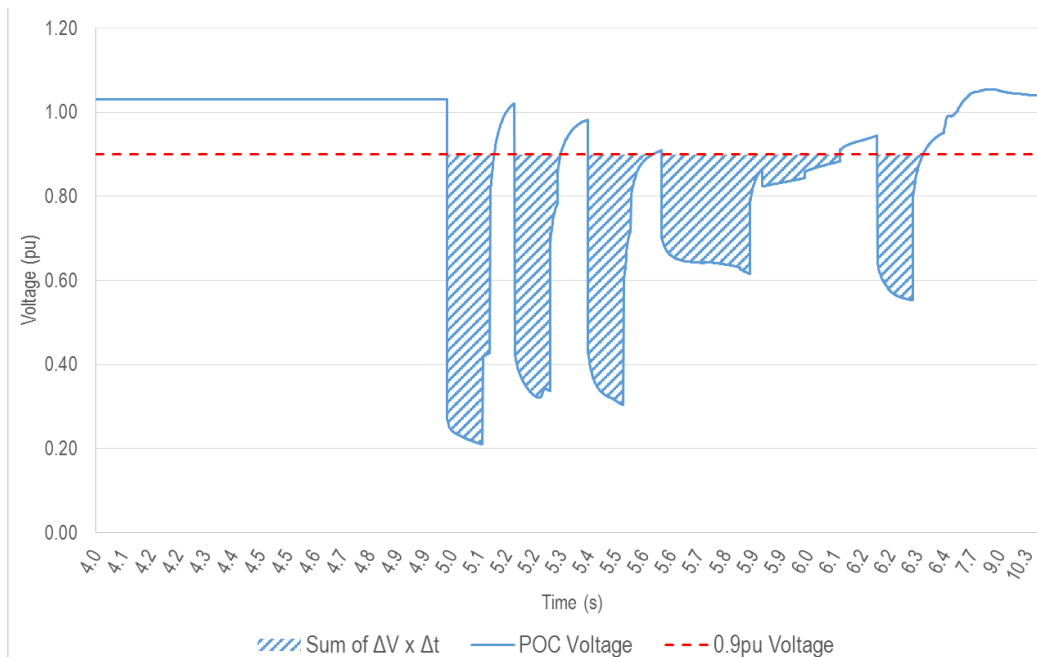
### 3.1.2 Number of disturbances ( $N_F$ )

This is the total number of power system disturbances calculated in a sliding time window of five or 30 minutes, for the automatic and minimum access standards, respectively. These disturbances would result in a voltage drop at the generating system’s connection point. The only disturbances to be considered are voltage disturbances resulting from natural power system disturbances, excluding any voltage disturbances due to the incorrect design of a control system<sup>2</sup>.

### 3.1.3 Sum of changes in voltage by the duration of the disturbance ( $\Delta V \times \Delta t$ )

This is the time integral of voltage difference between 90% of the normal connection point voltage and the connection point voltage during disturbances when the connection point voltage is lower than 90%. The ( $\Delta V \times \Delta t$ ) is measured in per-unit seconds (pu.s) where 90% normal voltage represents 0.9 per unit. This is shown in Figure 4.

**Figure 4 Calculation of  $\Delta V \times \Delta t$**



<sup>1</sup> Note that to assess whether a generating system is subject to realistic operational conditions during and after multiple voltage disturbances, the system strength as measured by the short circuit ratio (SCR) is calculated before and after the application of all disturbances to ensure that the post-contingency SCR is above the minimum SCR withstand capability of the generating system and its constituent generating units. Any sequence of disturbances resulting in the post-contingency SCR to drop below the minimum SCR withstand capability of the generating system was not studied.

<sup>2</sup> This phenomenon is discussed further in Appendix B.



The blue curve is the connection point voltage profile, while the red dashed horizontal line indicates 90% normal voltage. The shaded area is defined as  $\text{Sum of } \Delta V \times \Delta t$  for this particular example, in pu.s. For long, shallow faults, this criterion could be the first met.

## 4. APPLICATION OF PROPOSED REQUIREMENTS DURING GPS NEGOTIATION STAGE

A series of power system simulation studies should be performed by the Applicant, forming the basis of their proposed generator performance standards (GPS).

These simulation studies must include a range of power system operating scenarios, under which the proposed generating system's capability to ride through multiple disturbances is to be assessed, including different power system load levels and different generation dispatch patterns. These scenarios must at least include typical power system loading profile and dispatch patterns, which can be found in system snapshot data obtained from AEMO<sup>3</sup>. The Applicant must also consult with the connecting NSP regarding whether other specific network conditions must be included in these assessments.

For each simulation study, disturbances applied should be consistent with those described in the "Types of disturbances to be considered" in Table 2. Region and site-specific fault clearance times, including auto-reclose times, should be used in these simulations.

The Applicant may apply a random combination of fault locations, and fault types subject to meeting the criteria set out in Table 2. AEMO and the connecting NSP may advise on the appropriateness of any selected fault combinations, and require the Applicant to include specific fault combinations in the assessment.

## 5. SIMULATION CASE STUDIES TO SUPPORT THE PROPOSED REQUIREMENTS

AEMO conducted PSS@E simulation<sup>4</sup> case studies to confirm that the proposed access standards can be met by new and existing generating systems. The simulations were conducted using actual data and simulation models sourced from proposed and existing generation.

It is understood that simulation models of synchronous and, in particular, asynchronous generating systems might not account for all susceptibility mechanisms with respect to multiple voltage disturbances in quick succession. The focus of simulation studies presented in this section is to demonstrate that the power system to which these generating systems are connected will remain stable and operable in response to a number of voltage disturbances in quick succession, and to confirm the suitability and practicality of the levels of the three assessment criteria set out in Section 3.

Each assessment applied the maximum number of disturbances permitted by the proposed access standards, which can be manually or randomly applied during the simulation. In the simulation, the deep disturbances were manually selected and applied, while the remaining disturbances were randomly selected using simulation scripts. Where the disturbances were randomly applied, they were selected

<sup>3</sup> Provision of Network Data policies, and Data Provision Request Forms are available at: <https://www.aemo.com.au/Electricity/National-Electricity-Market-NEM/Data/Network-Data/Policy-on-provision-of-network-data>.

<sup>4</sup> The use of an EMT-type simulation tool such as PSCAD™/EMTDC™ will provide a more accurate representation of the response of generating systems under unbalanced network fault conditions. This will be particularly valid under low system strength conditions. The overall integrated models of all regions in such simulation tools are not currently available, but are expected to be developed within 12 months following the publication of *Power System Model Guidelines*. To gain confidence in the accuracy of PSS@E simulation studies for assessing the response of various generating systems to multiple voltage disturbances, a benchmarking study was conducted for a wind farm under medium system strength conditions for a region where AEMO has already developed the full integrated EMT-type model in PSCAD. This analysis is presented in Appendix E.

according to the “Type of disturbance to be considered” in Table 2. Disturbances were selected to avoid islanding.

For wind and solar farm assessments, the post-contingency weighted SCR at the connection point was calculated to ensure the SCR, accounting for the impact of nearby generating systems, is above the minimum SCR withstand capability of the generating units assessed.

For all simulations, the disturbance clearance and auto-reclose times were consistent with the fault clearance times and auto-reclosure requirements in different regions. It should be noted that all active and reactive power values in the simulation plots are based on a 100 MVA base. For example, a 2.0 pu active power is equal to 200 MW.

### 5.1.1 Simulation results summary

Table 4 presents the generating systems reported on, and which criteria (as proposed in Section 3) are met following assessment of each generating system.

The results show that the generating systems investigated can meet the *Total number of disturbances* ( $N_F$ ) criterion in simulation, with some cases simultaneously meeting the *Accumulated disturbance duration* ( $\Delta t$ ) criterion. One case shows the *Sum of  $\Delta V \times \Delta t$*  ( $\Delta V \times \Delta t$ ) criterion is met. Hence, with at least one of the criteria being met in every case, the generating systems can meet at least the minimum proposed access standard, with the asynchronous generating systems meeting the automatic access standard.

To ensure the power system to which the generating system under consideration is connected will remain stable, and that there is a sufficient margin between system stability limits and the proposed assessment criteria, several simulation case studies were conducted where at least one of the three criteria was increased above the proposed level for the respective access standards.

For example, in Case 5-3 (presented in Table 5) the *Accumulated disturbance duration* ( $\Delta t$ ) was increased to 2309 ms as opposed to 1800 ms as defined in the proposed automatic access standard.

**Table 4 Generating systems investigated in the assessment**

Technology	Project Status	Connection	System Strength <sup>A</sup>	Levels of Inter-connection <sup>B</sup>	Limiting Factor <sup>C</sup>
Synchronous generating system in highly interconnected transmission network	Existing	Transmission	N/A <sup>D</sup>	6	$N_F$ , $\Delta t$ of minimum access standard
Synchronous generating system in transmission network with little interconnection	Existing	Transmission	N/A <sup>D</sup>	1	$N_F$ of minimum access standard
Solar farm in distribution network with little interconnection	Committed	Distribution	Medium	1	$N_F$ , $\Delta t$ of automatic access standard
Solar farm in highly interconnected transmission network	Committed	Transmission	High	6	$N_F$ of minimum access standard
Wind farm in transmission network with little interconnection	Committed	Transmission	Medium	2	$N_F$ , $\Delta t$ of minimum access standard
Solar farm in distribution network (with highly interconnected transmission network upstream)	Committed	Distribution	Low	4	$\Delta V \times \Delta t$ of automatic access standard





- A. System strength is calculated as the pre-contingency Weighted Short Circuit Ratio (WSCR) at the connection point of the generating system. When the generating system is a committed project, the WSCR calculation only considers the committed project and nearby existing generating systems. No other committed project is considered in these aggregate SCR calculations. A WSCR>5 is considered as high, 3<WSCR<5 as medium, and WSCR<3 as low system strength conditions.
- B. The level of interconnection is defined as the number of circuits connecting a transmission busbar (110 kV and above) into which the generating system connects, to the rest of the power system. Double circuits mounted on the same tower are considered as two circuits.
- C. These are the assessment criteria met by the generating system under consideration.
- D. This is because the instability mechanism associated with synchronous machines is generally manifested through rotor angle instability and loss of synchronism, as opposed to low SCR conditions. For this reason, the use of SCR is not the most appropriate metric for assessing instability of synchronous machines under varying levels of system strength conditions.

The *Total number of disturbances* ( $N_F$ ), the *Accumulated disturbance duration* ( $\Delta t$ ), and the *Sum of  $\Delta V \times \Delta t$*  ( $\Delta V \times \Delta t$ ) are calculated for each simulation case and presented in Table 5.

**Table 5 Simulation results for generation successfully riding through multiple disturbances**

Generator	Case ID	Sum of $\Delta V \times \Delta t$	Total disturbance duration	Total no. of disturbances	No. of deep disturbances	Pre-contingency aggregate SCR	Post-contingency aggregate SCR
Synchronous generator in highly interconnected transmission network	1a-1	0.306	0.971	6	3	N/A <sup>B</sup>	N/A <sup>B</sup>
	1a-2	0.321	0.987	6	3		
	1a-3	0.371	1.162	6	3		
Synchronous generator in transmission network with little interconnection	2-1	0.377	0.912	6	3	N/A <sup>B</sup>	N/A <sup>B</sup>
	2-2	0.430	0.987	6	3		
	2-3	0.366	0.891	6	3		
Solar farm in distribution network with little interconnection	3-1	0.525	2.071	15	6	3.52	3.32
	3-2	0.512	1.923	15	6		3.21
	3-3	0.574	2.016	15	6		3.19
Solar farm in highly interconnected transmission network	4-1	0.492	1.578	15	5	7.77	4.41
	4-2	0.533	1.749	15	5		5.72
	4-3	0.552	1.767	15	5		5.43
Wind farm in transmission network with little interconnection	5-1	0.573	1.764	15	6	3.73	1.45
	5-2	0.572	1.815	15	6		1.73
	5-3	0.573	2.309	15	6		1.76
Solar farm in distribution network connecting into highly interconnected transmission network	6-1	1.013	1.705	5	5	1.99 <sup>A</sup>	1.80

A. Although the upstream transmission network is highly interconnected, the solar farm is radially fed from the distribution network to which the solar farm is connected, thus making the SCR very low.

B. This is because the instability mechanism associated with synchronous machines is generally manifested through rotor angle instability and loss of synchronism, as opposed to low SCR conditions. For this reason, the use of SCR is not the most appropriate metric for assessing instability of synchronous machines under varying levels of system strength conditions.

The following sections discuss the detailed results for each simulation case.

### 5.1.2 Synchronous generating system in highly interconnected transmission network

Cases 1a-1, 1a-2, and 1a-3 (Figure 5, Figure 6, and Figure 7 in Appendix A) investigated the multiple-fault ride-through performance of a synchronous generating system connected to a highly interconnected transmission network.

This generating system was assessed against the proposed minimum access standard, where it is required to ride through six disturbances, three of which would be deep disturbances. The generating system rode through six disturbances in all three cases. Since it met the proposed *Total number of disturbances* criterion, it can meet the proposed minimum access standard.

No case exceeded the proposed *Sum of  $\Delta V \times \Delta t$*  criterion, therefore, the capability to meet this criterion was not tested. Assessment against this criterion was unnecessary as the other criteria were satisfied.

The rotor angles presented in the simulation results in Appendix A are **relative** angles, calculated using the actual rotor angle of a nearby large synchronous generating system as a reference. These **relative** rotor angles are to show whether the generating system under investigation is in synchronism with the rest of the power system.

### 5.1.3 Synchronous generator in transmission network with little interconnection

Cases 2-1, 2-2, and 2-3 (Figure 8, Figure 9, and Figure 10 in Appendix A) investigated the multiple-fault ride-through performance of a synchronous generating system connecting to a transmission network, with little interconnection to the rest of the power system.

As with Case 1a, this generating system can meet the proposed minimum access standard, with the proposed *Total number of disturbances* criterion met in all three cases.

### 5.1.4 Solar farm in distribution network with little interconnection

Cases 3-1, 3-2, and 3-3 (Figure 11, Figure 12, and Figure 13 in Appendix A) investigated the multiple-fault ride-through performance of a solar farm connecting to a distribution network.

This solar farm was assessed against the proposed automatic access standard, where it is required to ride through 15 disturbances, six of which would be deep disturbances. The solar farm rode through 15 disturbances in all three cases, and can meet the proposed automatic access standard. For each case, the aggregate SCR was calculated after all disturbances, and was confirmed to be above the generating system's minimum SCR withstand capability.

### 5.1.5 Solar farm in highly interconnected transmission network

Cases 4-1, 4-2, and 4-3 (Figure 14, Figure 15, and Figure 16 in Appendix A) investigated the multiple-fault ride-through performance of a solar farm connecting to a highly interconnected transmission network.

In all cases, the solar farm rode through 15 disturbances, however only five deep disturbances can be applied without islanding the solar farm or a large section of the transmission network. For each case, the SCR was calculated after all disturbances, and was confirmed to be well above the solar farm's minimum SCR withstand capability.

No case exceeded the proposed *Sum of  $\Delta V \times \Delta t$* , or the proposed *Accumulated disturbance duration* criteria. Nevertheless, the solar farm can meet the proposed automatic access standard, as it met the proposed *Total number of disturbances* criterion.

### 5.1.6 Wind farm in transmission network with little interconnection

Cases 5-1, 5-2, and 5-3 (Figure 17, Figure 18, and Figure 19 in Appendix A) investigated the multiple-fault ride-through performance of a wind farm connecting to a transmission network with little interconnection to the rest of the power system.

This wind farm was assessed against the proposed automatic access standard, where it is required to ride through 15 disturbances, six of which would be deep disturbances. The wind farm rode through 15 disturbances in all three cases, and can meet the proposed automatic access standard. For each case, the aggregate SCR was calculated after all disturbances, and was confirmed to be above the generating system’s minimum SCR withstand capability.

**5.1.7 Solar farm in distribution network with highly interconnected transmission network upstream (meeting  $\Delta V \times \Delta t$  criteria)**

Case 6-1 (Figure 20 in Appendix A) is presented to demonstrate that the proposed *Sum of  $\Delta V \times \Delta t$*  criterion can be met by this type of generating system.

This case investigated a solar farm connecting into a distribution network connecting into a highly interconnected transmission network. The results showed only five disturbances can be applied, all of which are deep disturbances. The resulting *Sum of  $\Delta V \times \Delta t$*  is 1.013 pu.s (meeting the proposed 1.0 pu.s threshold), while the *Accumulated disturbance duration* is 1.705 s, not meeting the proposed 1.8 s threshold. Since this solar farm met the proposed *Sum of  $\Delta V \times \Delta t$*  criterion, it can meet the proposed automatic access standard.

**5.1.8 Failure to ride through multiple disturbances**

The suite of PSS®E simulations also showed that, in some cases, the generating system failed to ride through multiple disturbances. Example case results are provided in Figure 21, Figure 22, and Figure 23 of Appendix A. These results were examined to check whether any of the criteria were violated. Table 6 summarises the results.

**Table 6 Simulation results of generator failing to ride through multiple disturbances**

Generator	Case ID	Sum of $\Delta V \times \Delta t$	Total Disturbance Duration(s)	Total no. of disturbances	No. of deep disturbances	Comments
Synchronous generator in highly interconnected transmission network	1b-1	0.513	1.301	6	3	<b>Criteria violated:</b> <ul style="list-style-type: none"> <li>Sum of <math>\Delta V \times \Delta t</math></li> <li>Total disturbance duration</li> </ul>
	1b-2	0.588	1.405	6	3	
	1b-3	0.505	1.224	6	3	

Where the generating system failed to ride through multiple disturbances, both the *Sum of  $\Delta V \times \Delta t$*  (0.5 pu.s) and *Accumulated disturbance duration* (1 s) were violated, in which case the generating system is not required to ride through such a disturbance sequence.

Under such a scenario, the synchronous generating system would be disconnected by its protection system to prevent damage to it.

It should be noted that the case presented in Table 6 was assessed with a maximum 100 ms time difference between two successive disturbances. This is shorter than the maximum 200 ms time difference between two successive disturbances proposed in the minimum access standard.

A shorter time difference was used to fully simulate a synchronous generating systems’ susceptibility to loss of synchronism conditions due to faults in quick succession. In these cases, even though the synchronous generating system failed to ride through the disturbance sequence, it does not mean the generating system cannot meet the proposed minimum access standard. This is because the same generating system was able to successfully ride through the faults when subjected to sequence of disturbances consistent with the assessment criteria for the proposed minimum access standard (these scenarios are discussed in case studies 1a-1, 1a-2 and 1a-3).

### 5.1.9 Impact on synchronous generating systems' auxiliary supplies

The impact on synchronous generating system auxiliary supplies from riding through multiple disturbances has been investigated to assess whether their withstand capability could be a limiting factor to the generating units' multiple disturbance ride-through capability.

As auxiliary supplies are not typically modelled in PSS@E, site-specific PSCAD™/EMTDC™ models have been used to simulate the performance of auxiliary supplies under a multiple-disturbance ride-through scenario.

The simulation results can be found in Appendix D.

The results indicated that no auxiliary load under investigation was tripped or stalled while the generating unit rode through multiple disturbances. This is an expected result, because the motors' under-voltage protection is typically in the order of 2-3 s, while the total disturbance duration in the proposed multiple-disturbance ride-through requirement is less than that. Thus, the limitations of auxiliary supplies for existing synchronous generating units will likely not be a key determining factor for their capability to ride through multiple disturbances.

For future synchronous generating systems, it will be the responsibility of the plant owners and equipment manufacturers to design the auxiliary supplies and the protection systems appropriately to meet the multiple-disturbance ride-through requirement.

### 5.1.10 Performance comparison between PSCAD™/EMTDC™ and PSS@E models

To gain confidence in the accuracy of the PSS@E simulation results, AEMO compared the multiple-disturbance ride-through performance of the PSCAD™/EMTDC™ model and the PSS@E model of a wind farm connecting into the transmission network with medium system strength conditions prior to the application of disturbances. A medium system strength condition was chosen to ensure the PSS@E simulation tool remained reasonably accurate for assessing the performance of the generating system.

In both the PSCAD™/EMTDC™ and PSS@E simulations, the same disturbance sequence, consisting of 15 disturbances, was applied to the wind farm model. In both simulations, the pre- and post-contingency SCR is above the wind turbines' minimum SCR withstand capability. The active power and the reactive power output of both wind farm models was compared, and is presented in Figure 36 and Figure 37 in Appendix E.

The results show similar performance in both the PSCAD™/EMTDC™ and PSS@E simulations for a multiple-disturbance ride-through event, and that the wind farm can ride through 15 disturbances, thus meeting the proposed automatic access standard.

## 6. CONCLUSION

The simulation results described in this report show that the proposed access standards for multiple-fault ride-through can be met by the generating systems considered in the assessment, using the proposed assessment methodology and criteria described in Section 3.

Where a generating system failed to ride through multiple disturbances, simulation results showed that such a disturbance sequence would result in violation of both the proposed *Sum of  $\Delta V \times \Delta t$*  and the *Accumulated disturbance duration* criteria. Generating systems, however, are not required to ride through such multiple disturbance sequences.

In all simulation cases, the total number of disturbances required by the proposed access standards has been met, which appears to be the most common restrictive criterion. The *Accumulated disturbance duration* and *Sum of  $\Delta V \times \Delta t$*  criteria could be the most restrictive criteria, where long and shallow disturbances would have a material impact on the connection point voltage.



Based on these findings, it is concluded the proposed access standards are practical, and can be met by various generation technologies.



# APPENDIX A. PSS®E SIMULATION RESULTS

Figure 5 Case 1a-1 Synchronous Generating System 1 Stable Case 1

Sync Generator in highly interconnected transmission network  
 $dV \times dT = 0.305688771808$ , POC voltage below 0.9pu for 0.971s  
Simulation Time:20180316\_134745

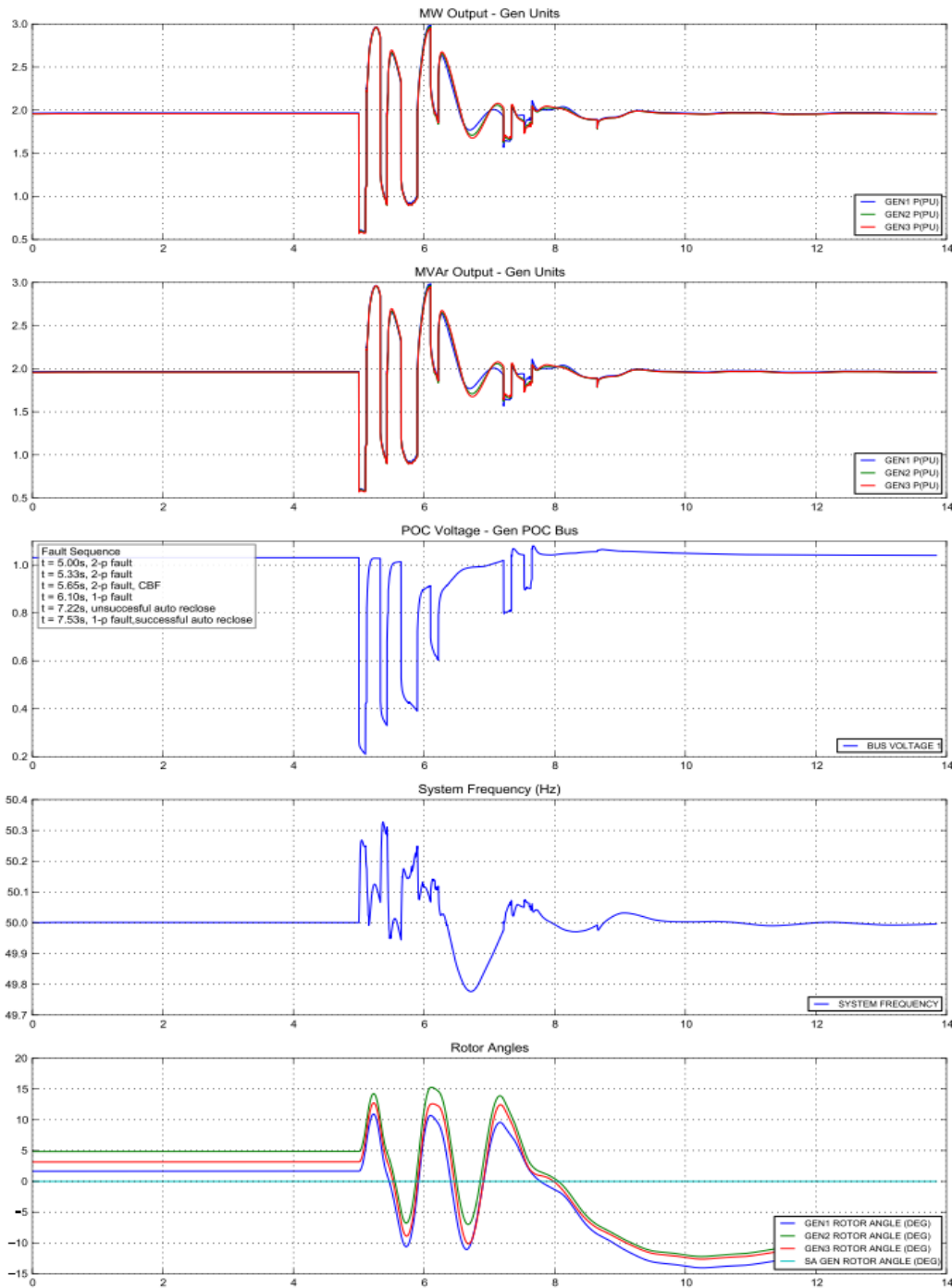
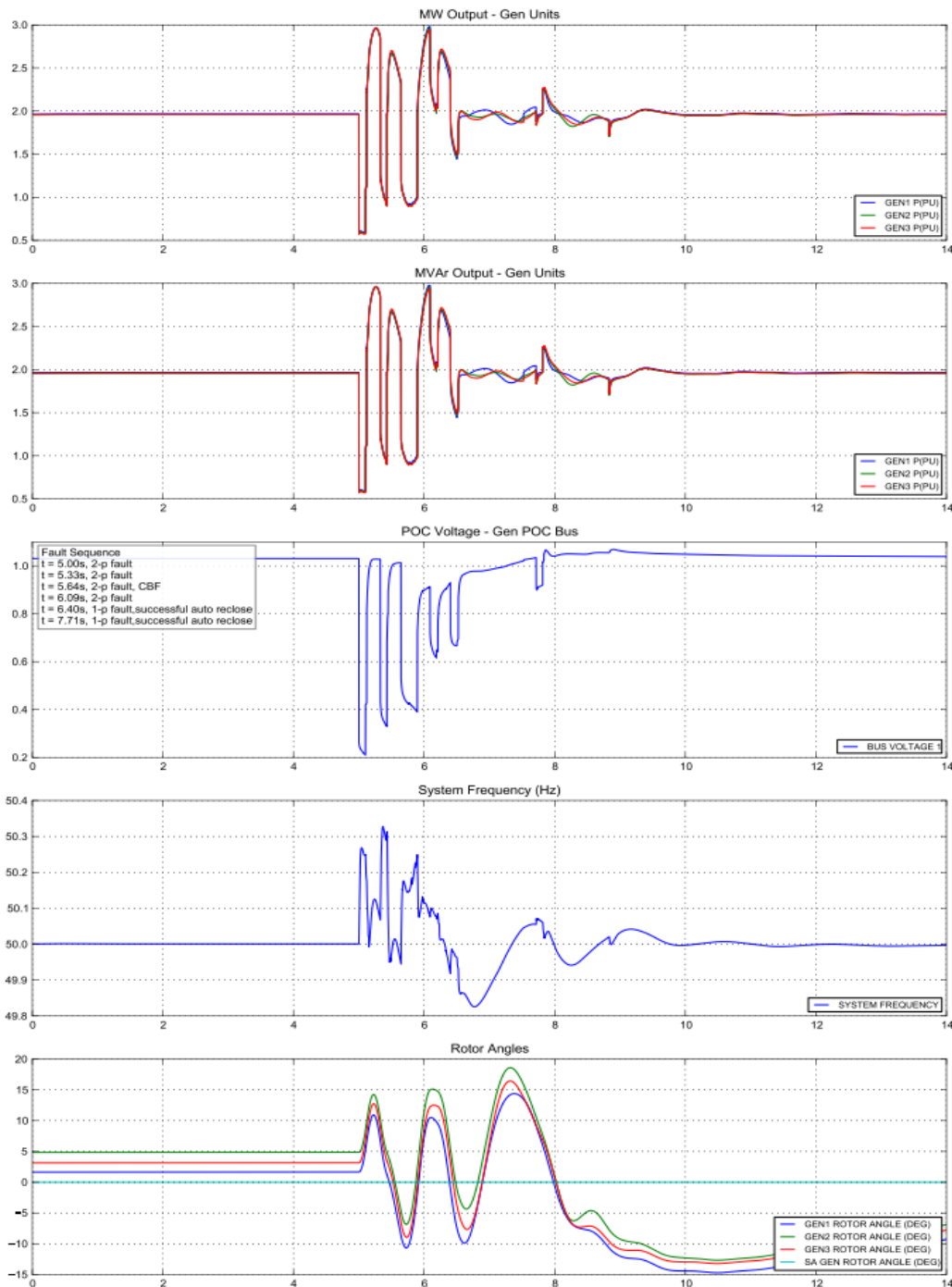






Figure 6 Case 1a-2 Synchronous Generating System 1 Stable Case 2

Sync Generator in highly interconnected transmission network  
 $dV \times dT = 0.320898587245$ , POC voltage below 0.9pu for 0.987s  
Simulation Time:20180316\_140430



**Figure 7 Case 1a-3 Synchronous Generating System 1 Stable Case 3**

**Sync Generator in highly interconnected transmission network  
 $dV \times dT = 0.371158059764$ , POC voltage below 0.9pu for 1.162s  
 Simulation Time:20180316\_140838**

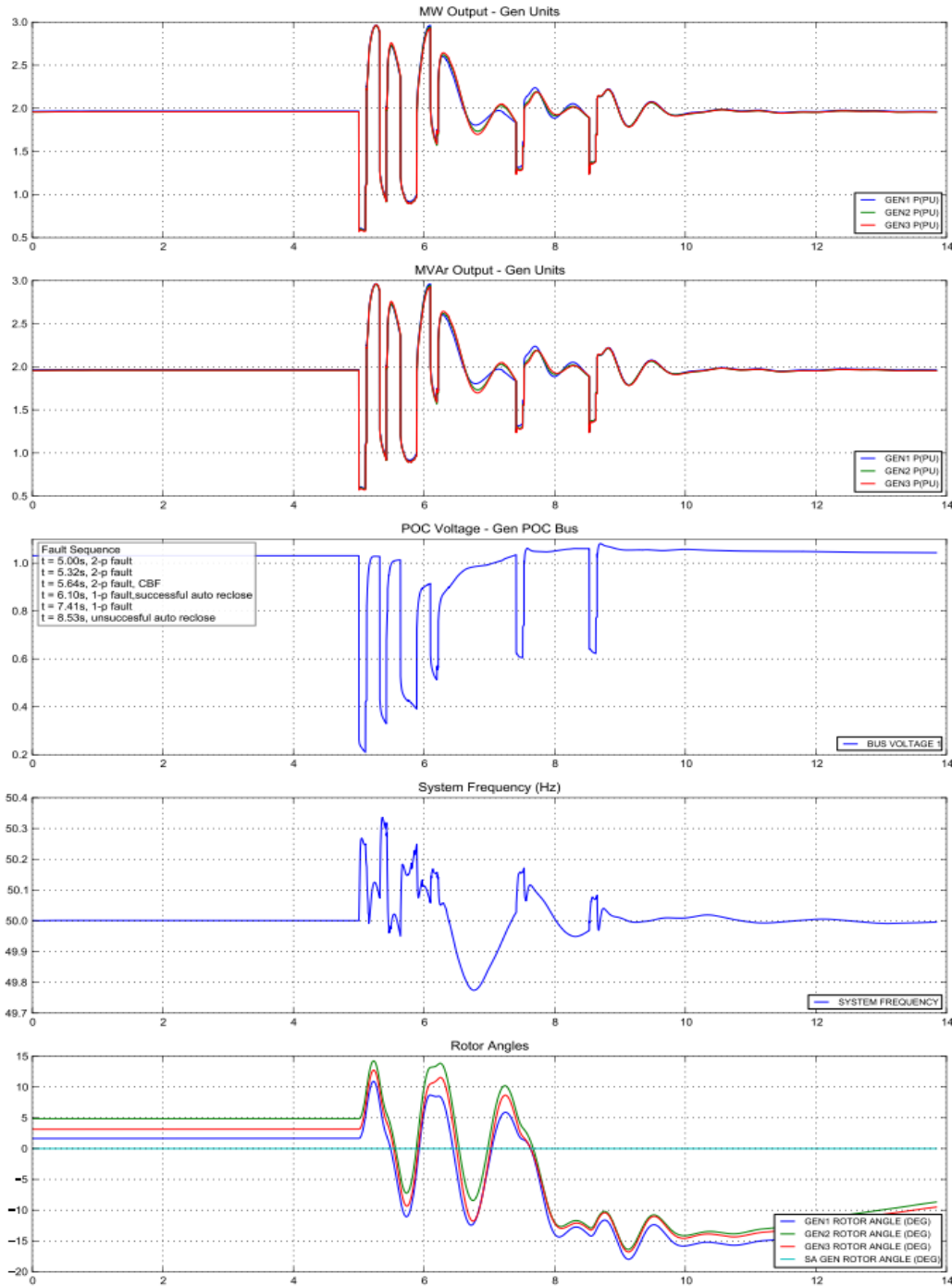




Figure 8 Case 2-1 Synchronous Generating System 2 stable Case 1

Sync Generator in transmission network with little interconnection  
 $dV \times dT = 0.377768767285$ , POC voltage below 0.9pu for 0.912s  
Simulation Time:20180315\_211320

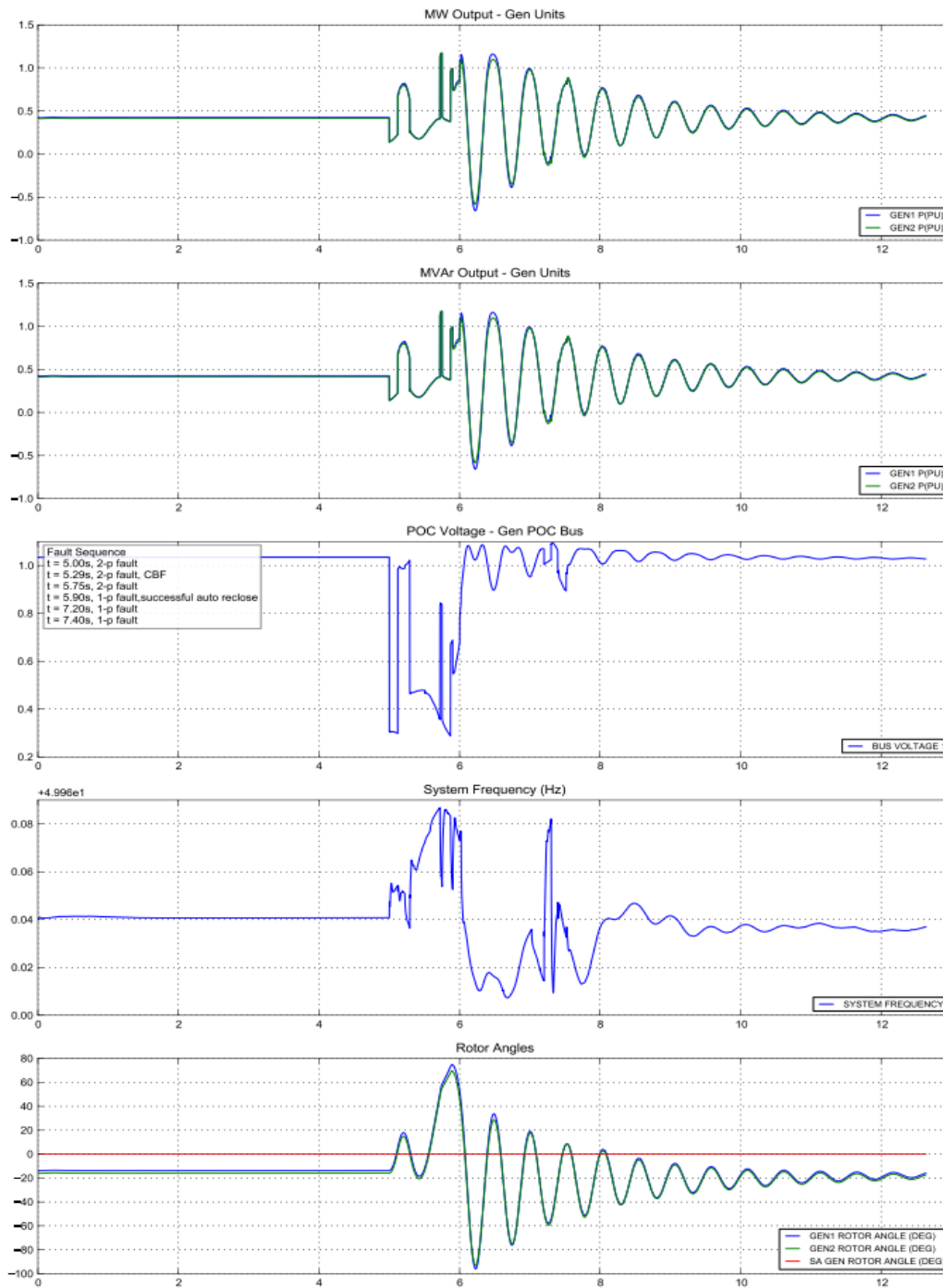




Figure 9 Case 2-2 Synchronous Generating System 2 stable Case 2

Sync Generator in transmission network with little interconnection  
 $dV \times dT = 0.43084848893$ , POC voltage below 0.9pu for 0.987s  
Simulation Time:20180315\_212008

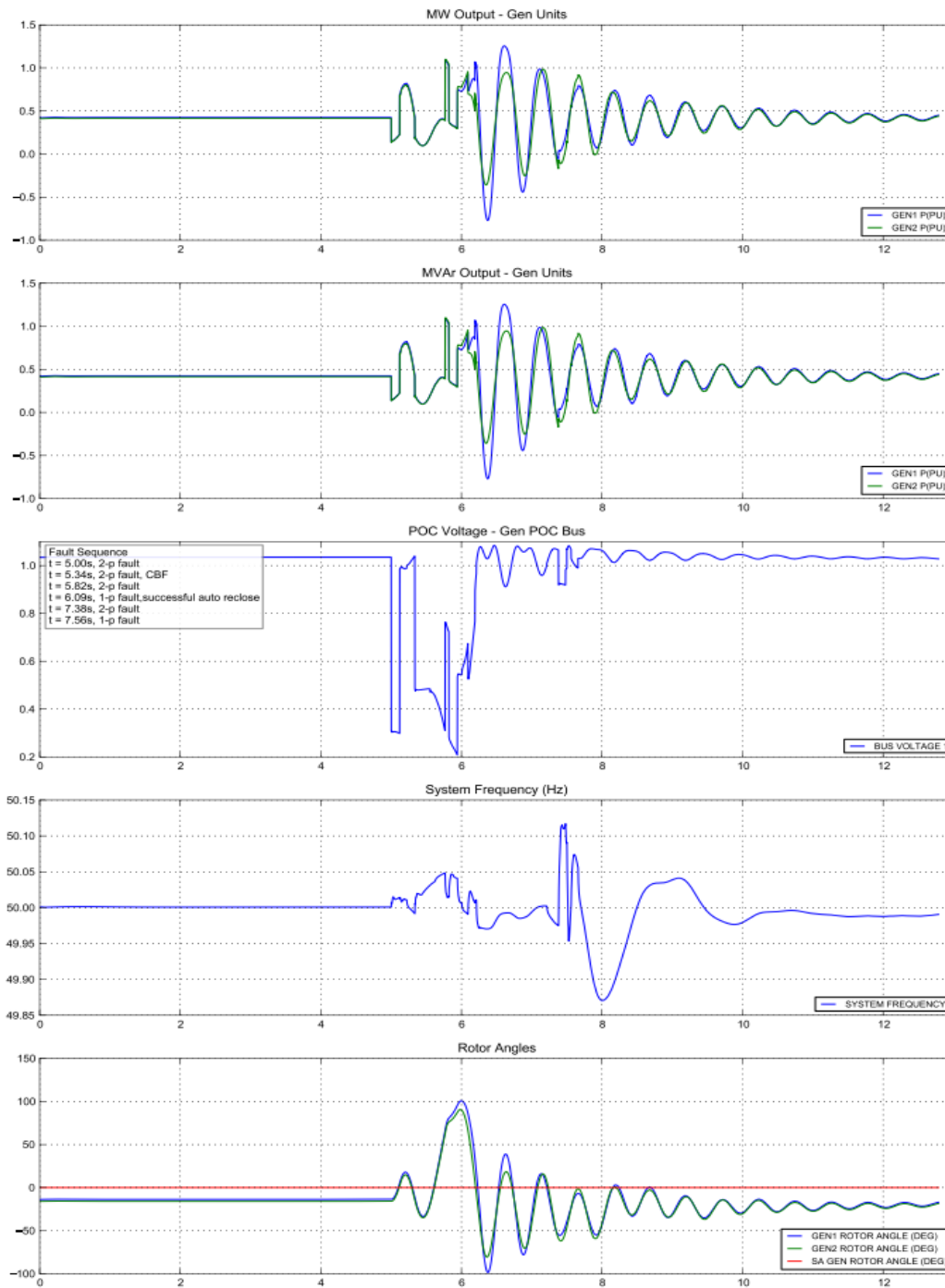




Figure 10 Case 2-3 Synchronous Generating System 2 stable Case 3

Sync Generator in transmission network with little interconnection  
 $dV \times dT = 0.366179712677$ , POC voltage below 0.9pu for 0.891s  
Simulation Time:20180315\_213603

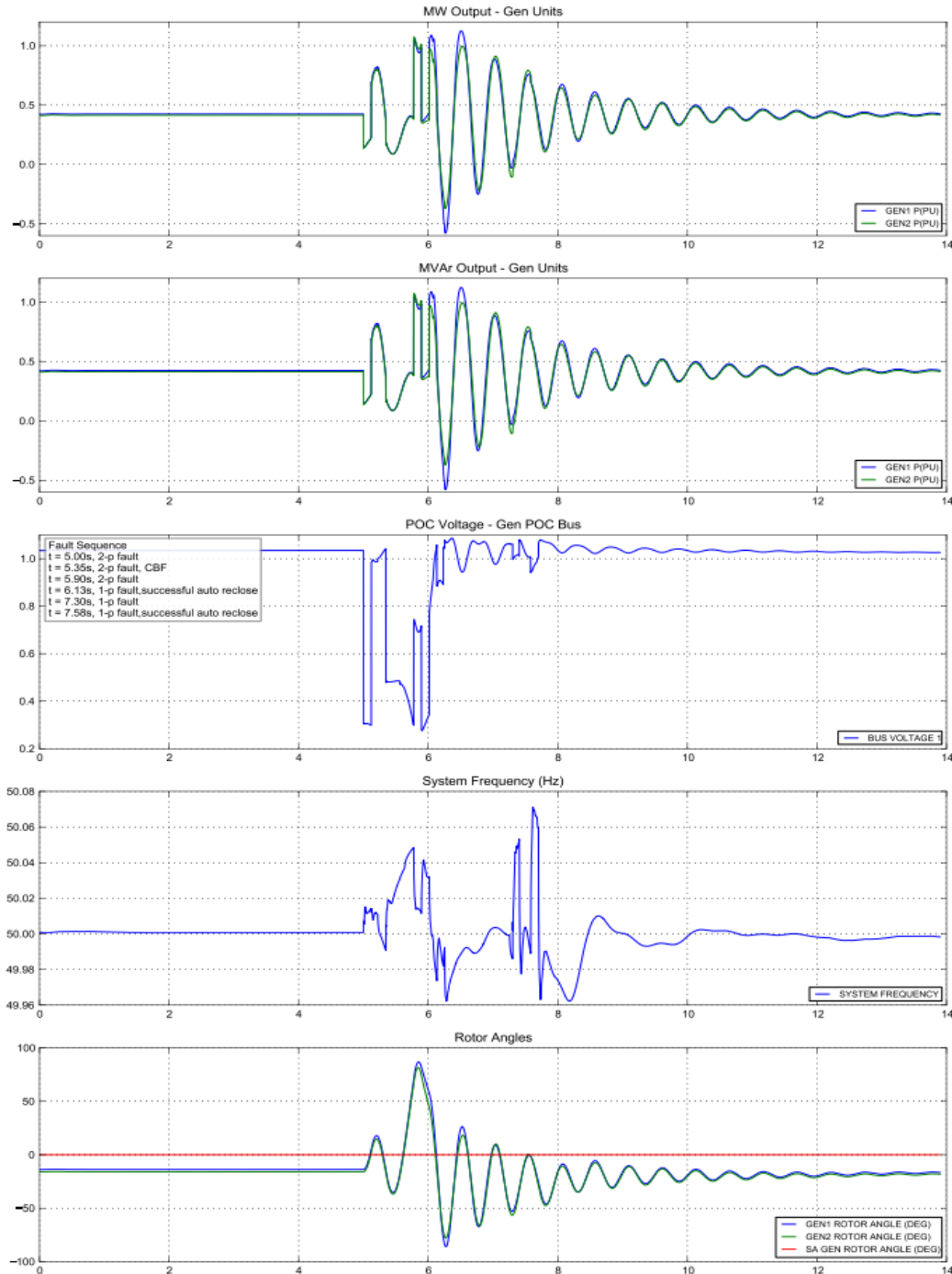




Figure 11 Case 3-1 Asynchronous Generating System 1 stable Case 1

Solar Farm in Distribution Network with little interconnection  
 $dV \times dT = 0.524916704381$ , POC voltage below 0.9pu for 2.071s  
Simulation Time:20180314\_171348

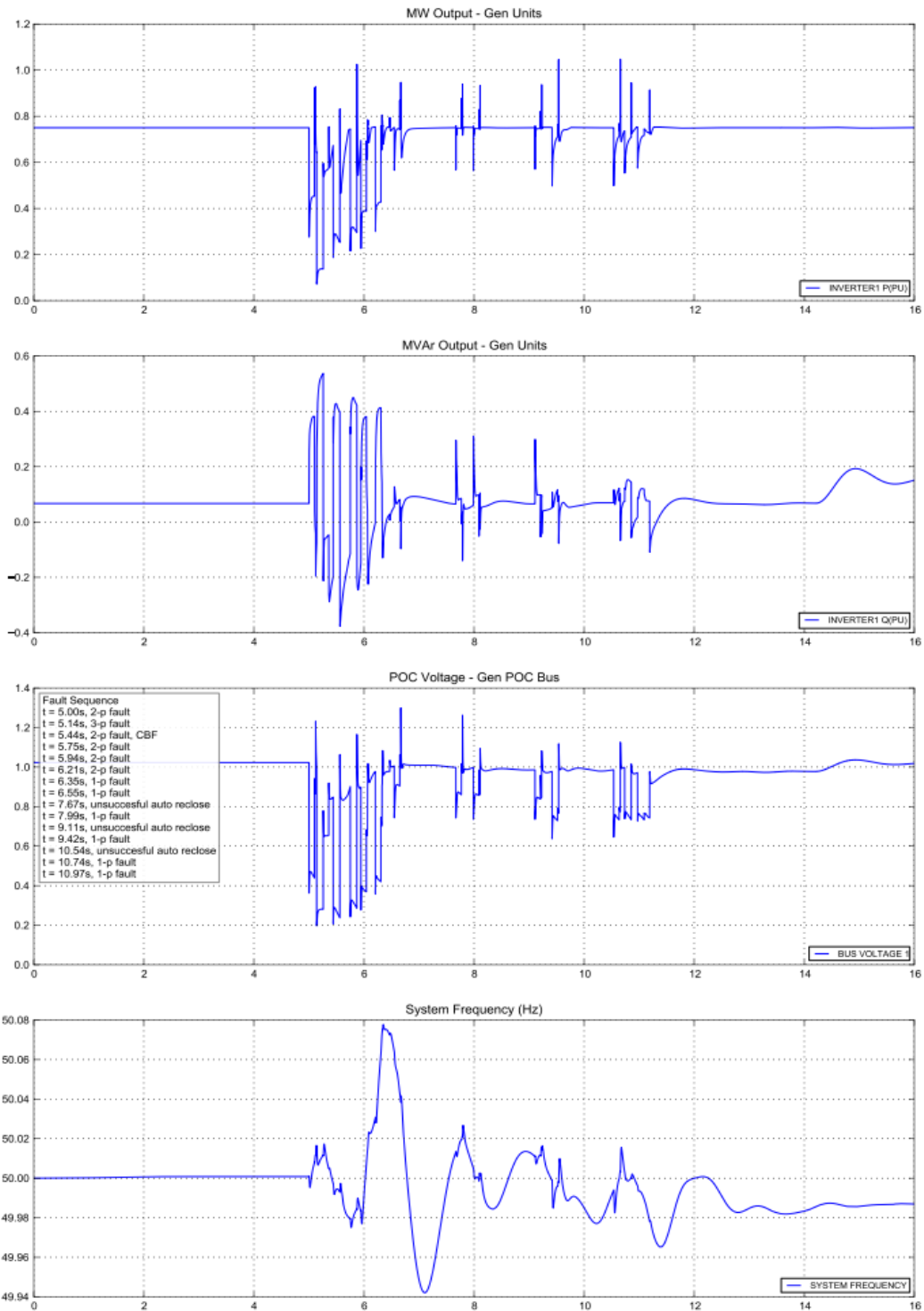






Figure 12 Case 3-2 Asynchronous Generating System 1 stable Case 2

Solar Farm in Distribution Network with little interconnection  
 $dV \times dT = 0.511641213906$ , POC voltage below 0.9pu for 1.923s  
Simulation Time:20180314\_223617

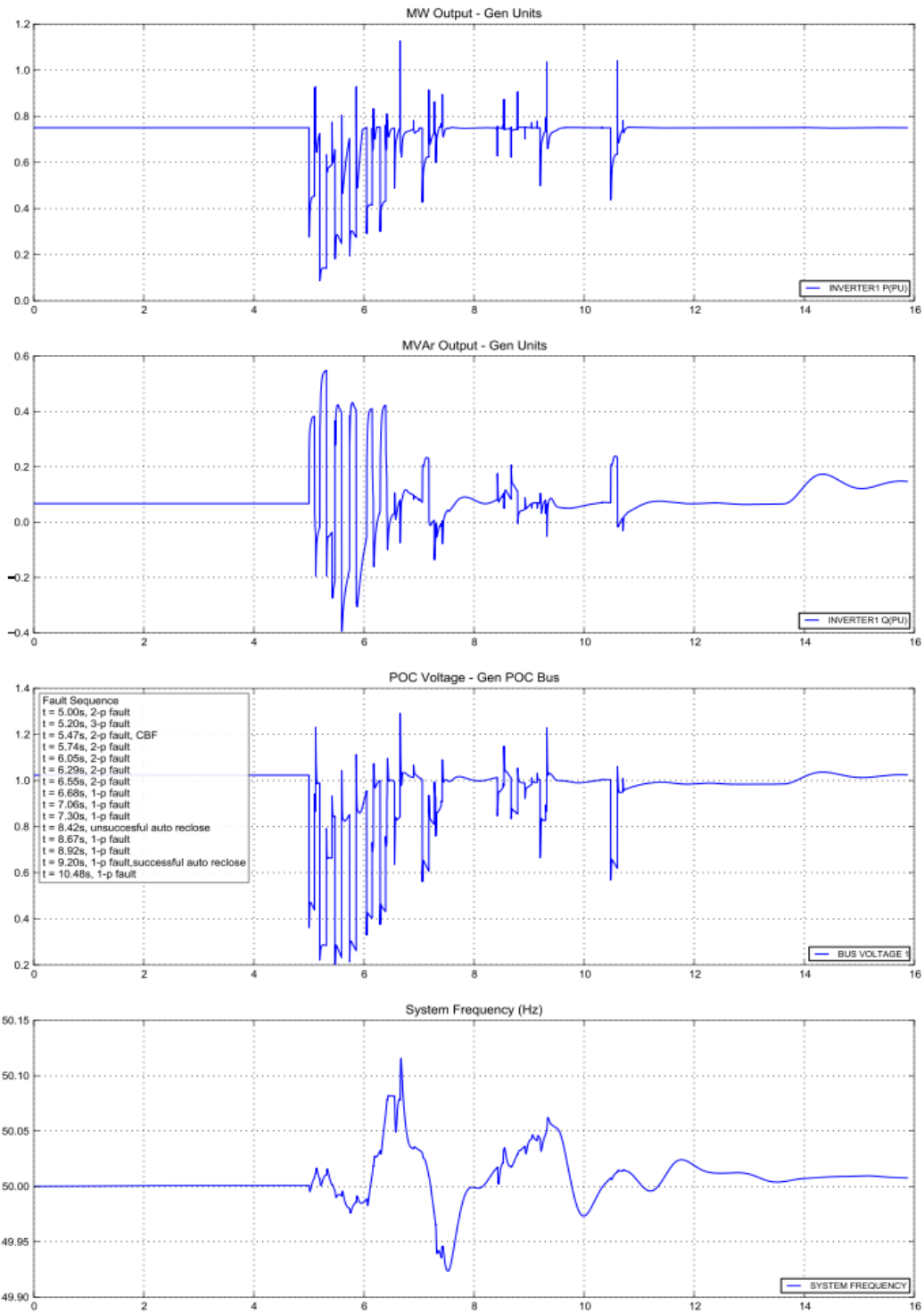




Figure 13 Case 3-3 Asynchronous Generating System 1 stable Case 3

Solar Farm in Distribution Network with little interconnection  
 $dV \times dT = 0.574122869486$ , POC voltage below 0.9pu for 2.016s  
Simulation Time:20180314\_223931

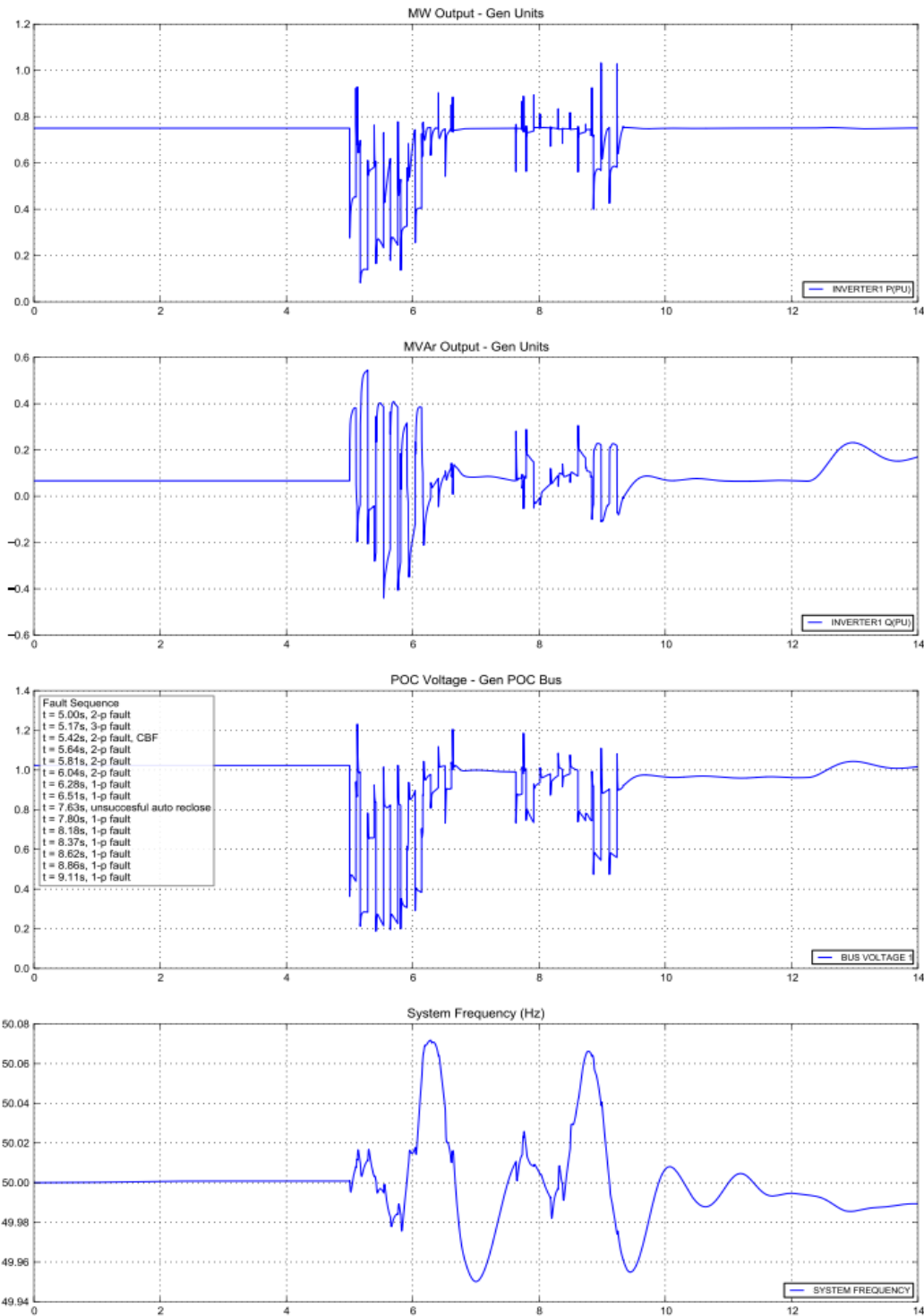




Figure 14 Case 4-1 Asynchronous Generating System 2 stable Case 1

Solar Farm in Highly Interconnected Transmission Network  
 $dV \times dT = 0.491766717552$ , POC voltage below 0.9pu for 1.578s  
Simulation Time:20180315\_103953

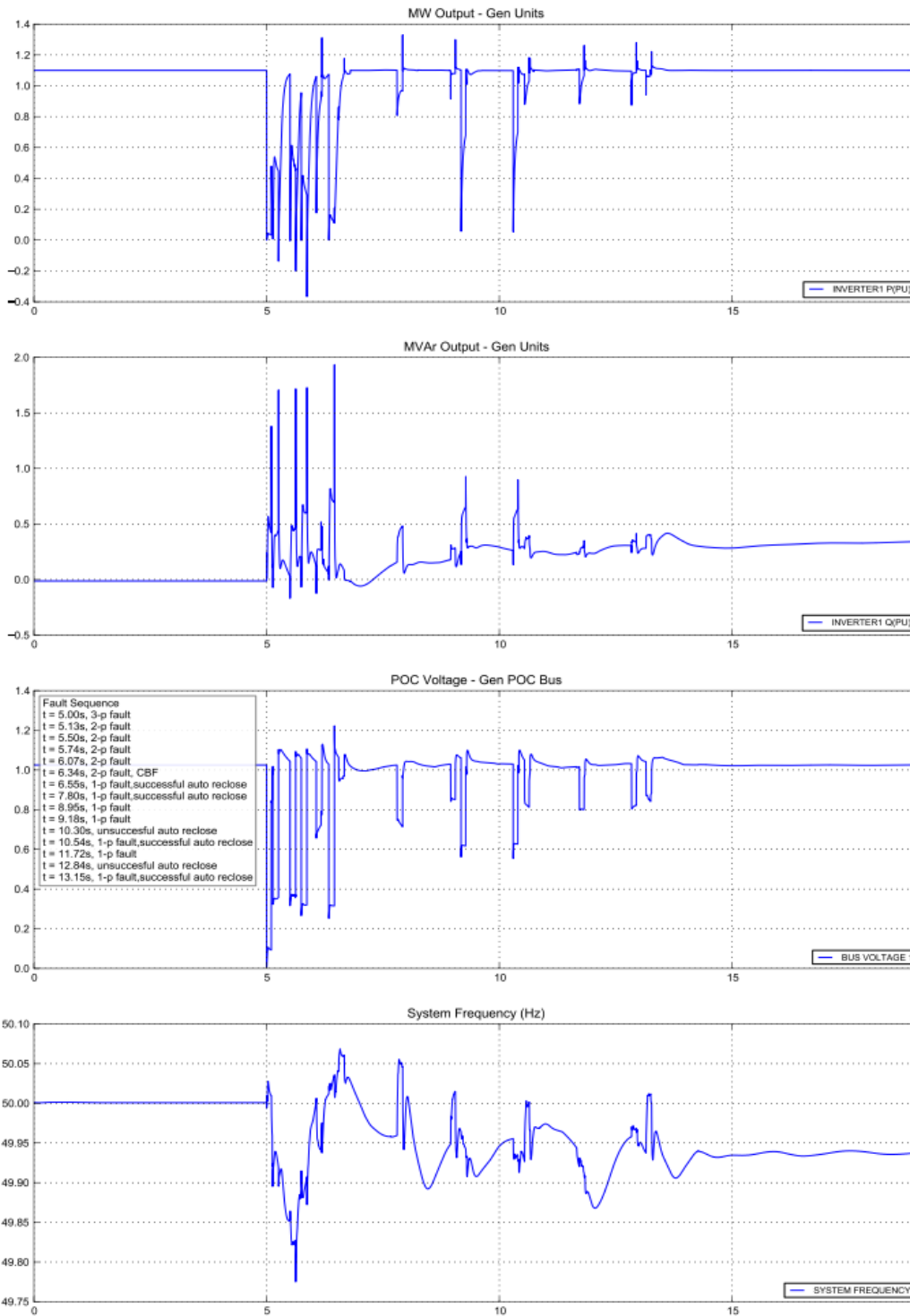




Figure 15 Case 4-2 Asynchronous Generating System 2 stable Case 2

Solar Farm in Highly Interconnected Transmission Network  
 $dV \times dT = 0.533390882068$ , POC voltage below 0.9pu for 1.749s  
Simulation Time:20180315\_111328

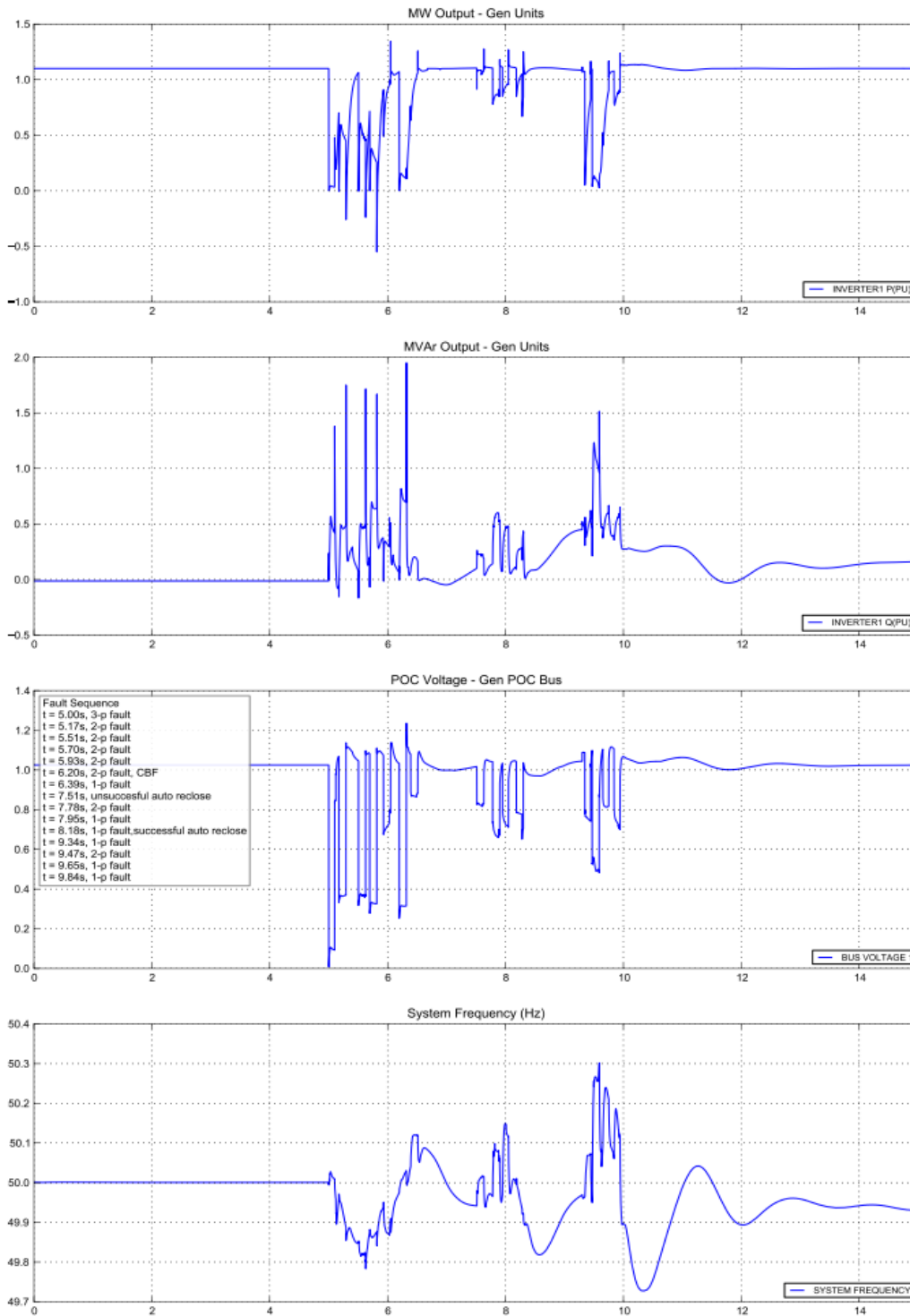




Figure 16 Case 4-3 Asynchronous Generating System 2 Stable Case 3

Solar Farm in Highly Interconnected Transmission Network  
 $dV \times dT = 0.551729133164$ , POC voltage below 0.9pu for 1.767s  
Simulation Time:20180315\_111330

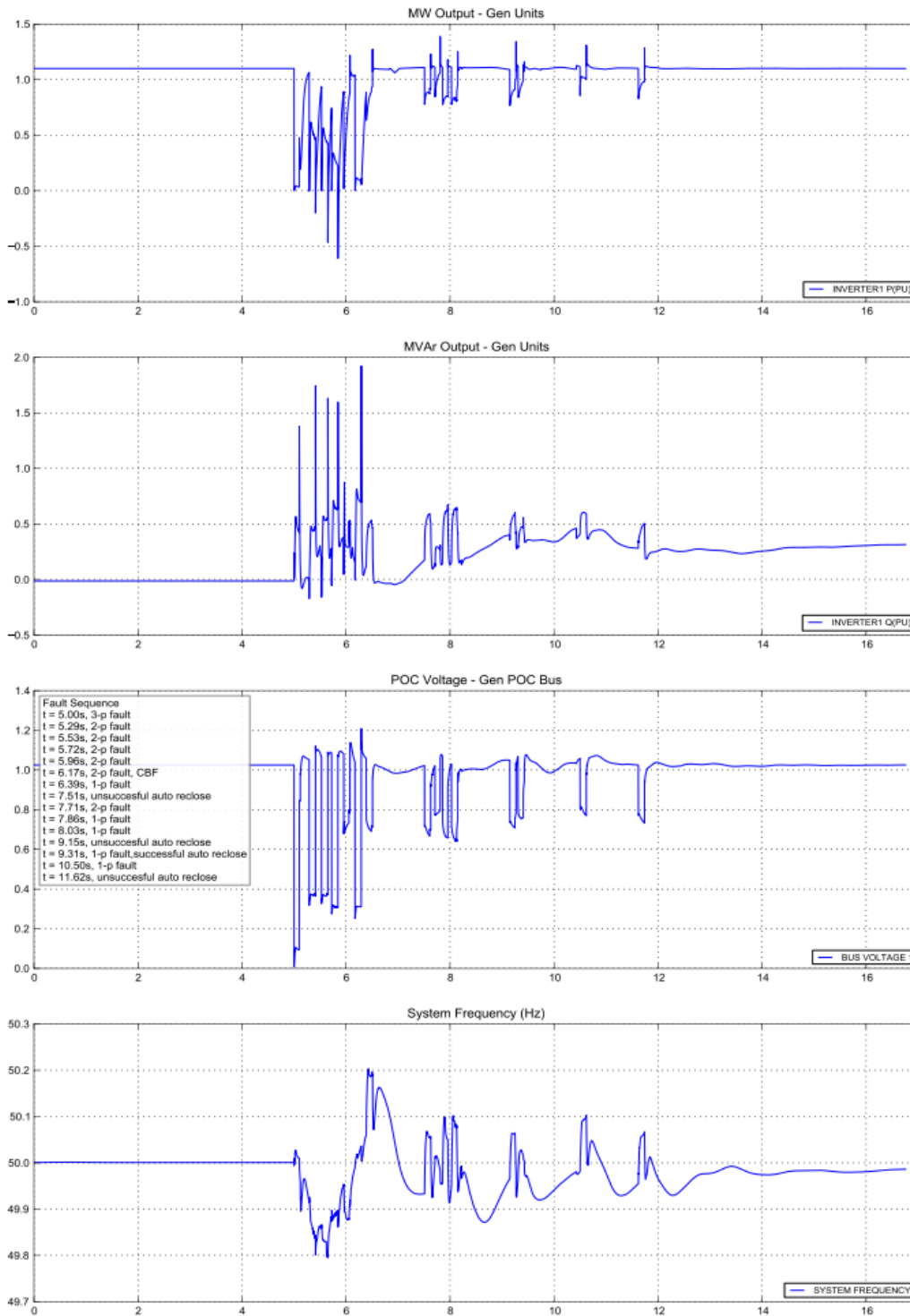




Figure 17 Case 5-1 Asynchronous Generating System 3 Stable Case 1

Wind Farm in Transmission Network with Little Interconnection  
 $dV \times dT = 0.572622567779$ , POC voltage below 0.9pu for 1.764s  
Simulation Time:20180315\_103522

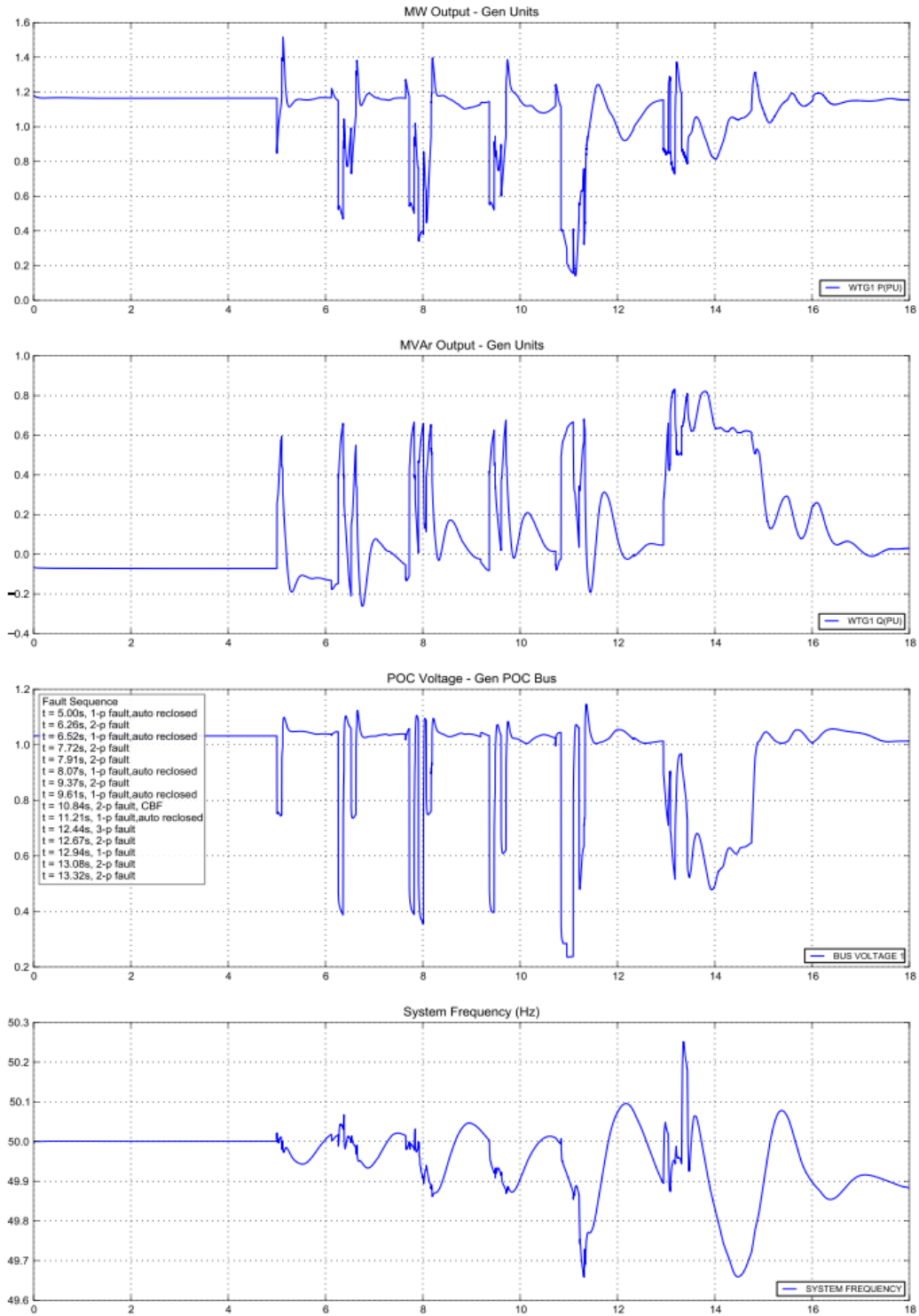




Figure 18 Case 5-2 Asynchronous Generating System 3 Stable Case 2

Wind Farm in Transmission Network with Little Interconnection  
 $dV \times dT = 0.572078975692$ , POC voltage below 0.9pu for 1.815s  
Simulation Time:20180315\_105557

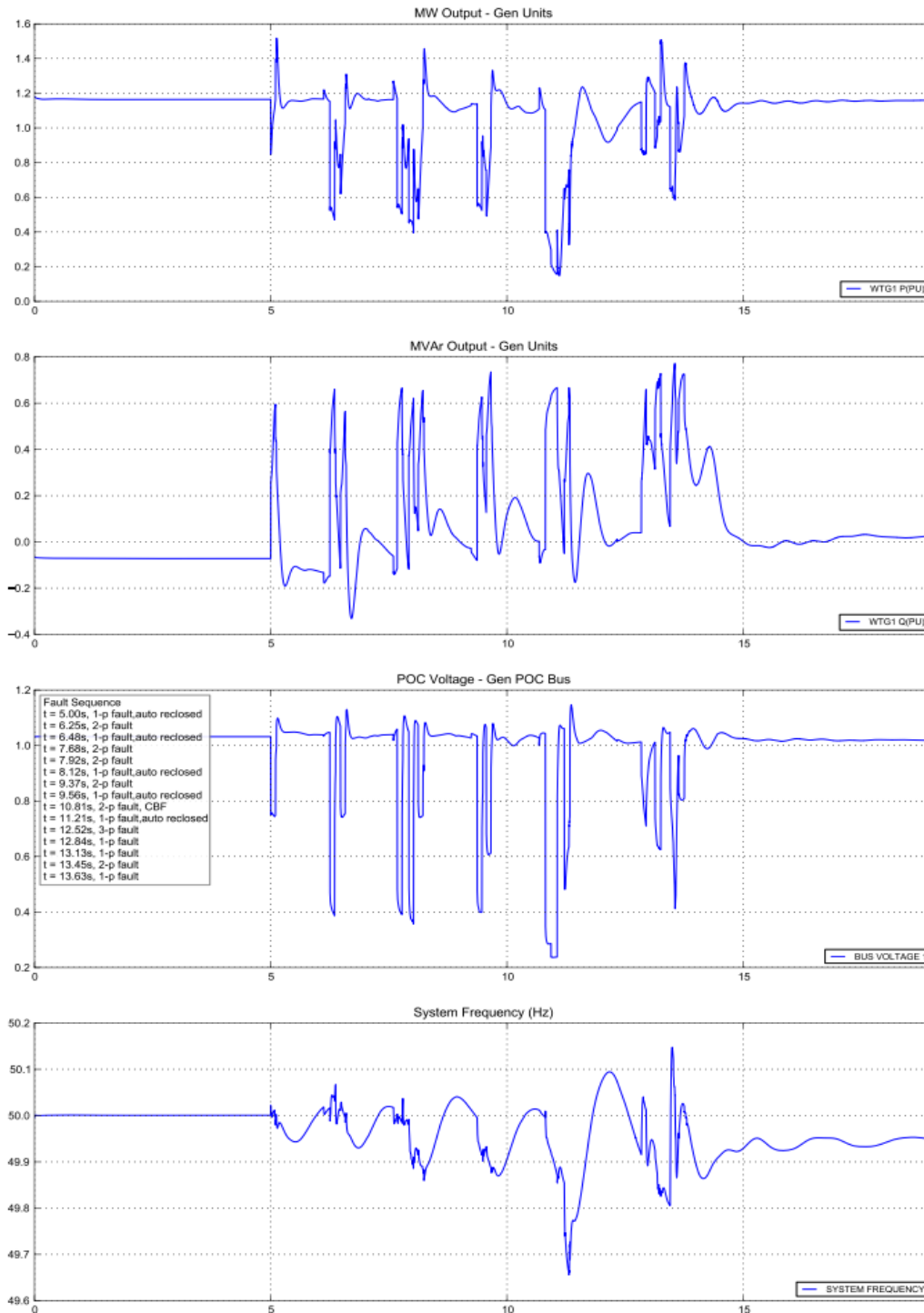






Figure 19 Case 5-3 Asynchronous Generating System 3 Stable Case 3

Wind Farm in Transmission Network with Little Interconnection  
 $dV \times dT = 0.573357006198$ , POC voltage below 0.9pu for 2.309s  
Simulation Time:20180315\_114032

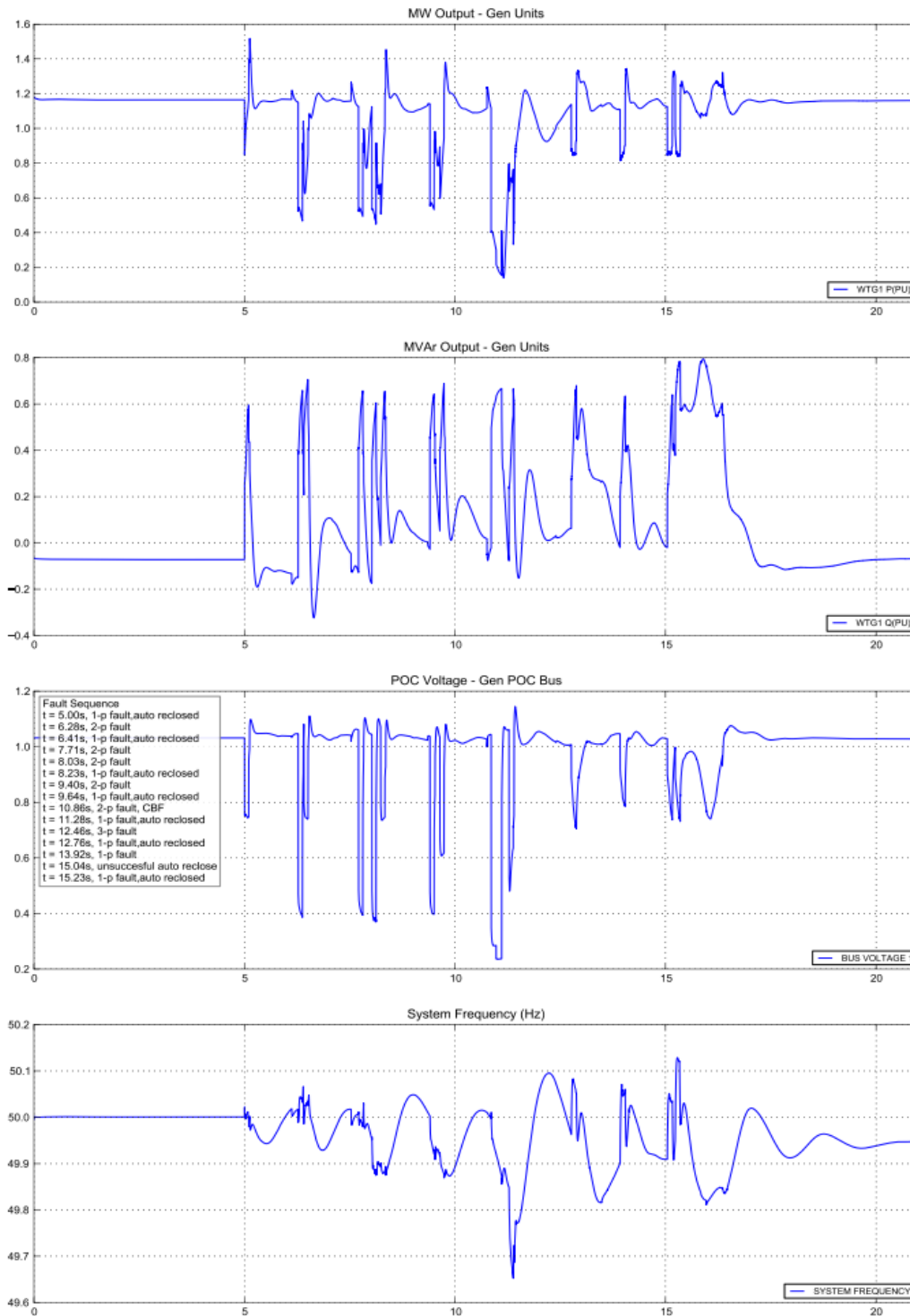




Figure 20 Case 6-1 Asynchronous Generating System 4 Stable Case

Simulation Time: .\OutFiles\20180308\_204835, Simulation Title: Solar farm in distribution network  
dV x dT = 1.0132025342, POC voltage below 0.9pu for 1.705s

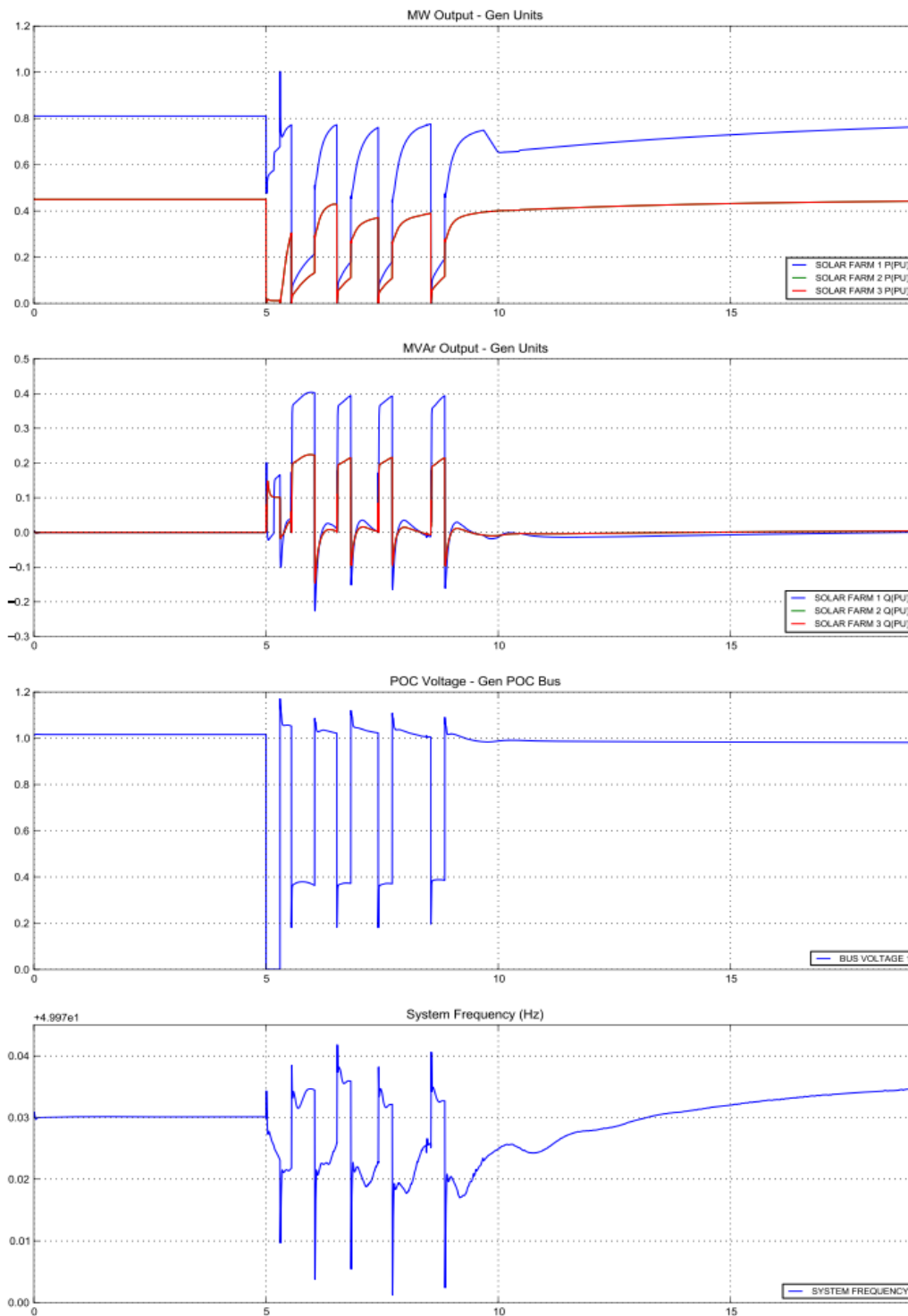




Figure 21 Case 1b-1 Synchronous Generating System 1 unstable Case 1

Simulation Time:20180125\_164037,Simulation Title:Sync Generator in highly interconnected transmission network  
dV x dT = 0.512526724899, POC voltage below 0.9pu for 1.301s

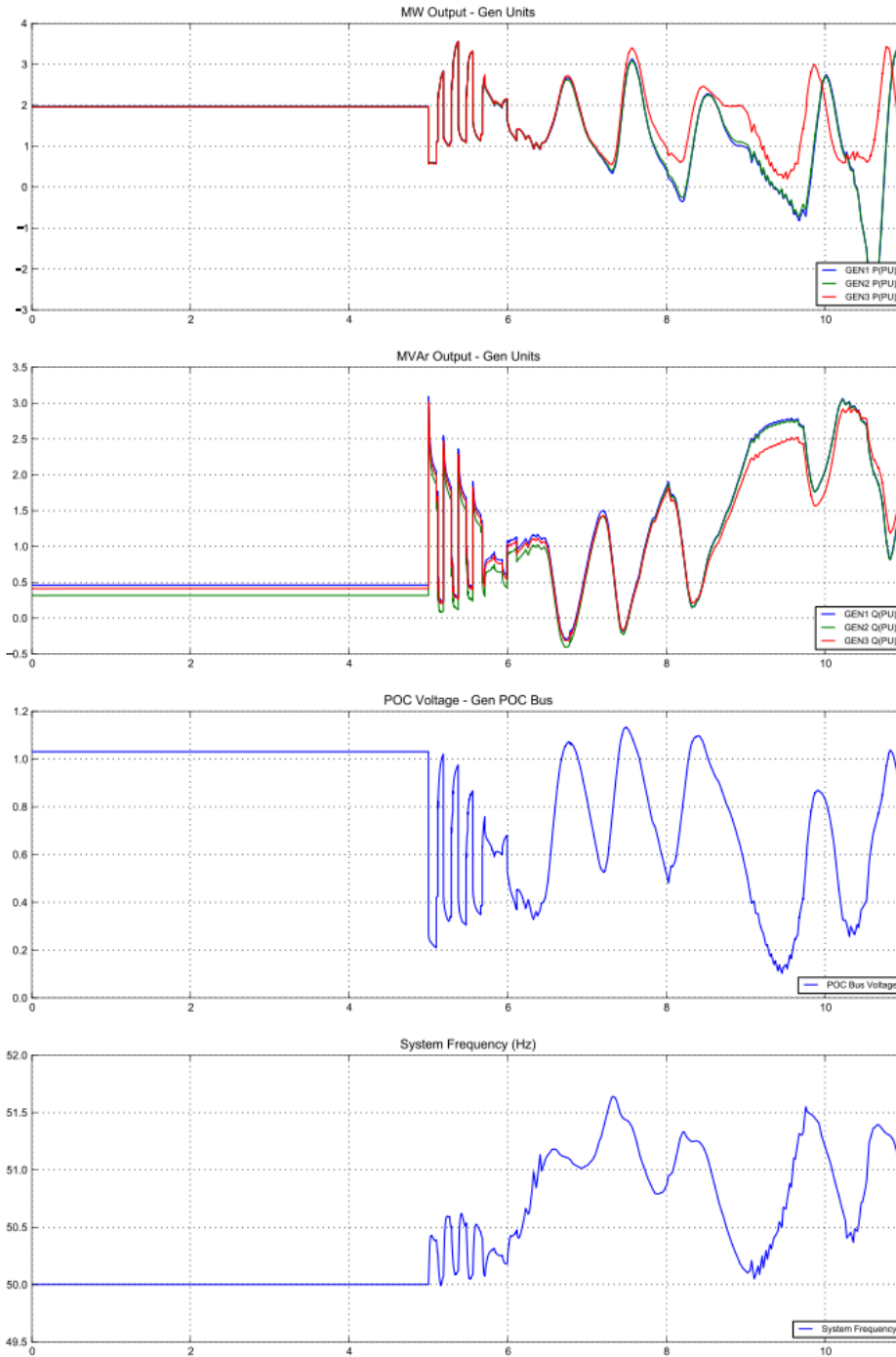




Figure 22 Case 1b-2 Synchronous Generating System 1 unstable Case 2

Simulation Time:20180125\_164832,Simulation Title:Sync Generator in highly interconnected transmission network  
dV x dT = 0.588173137825, POC voltage below 0.9pu for 1.405s

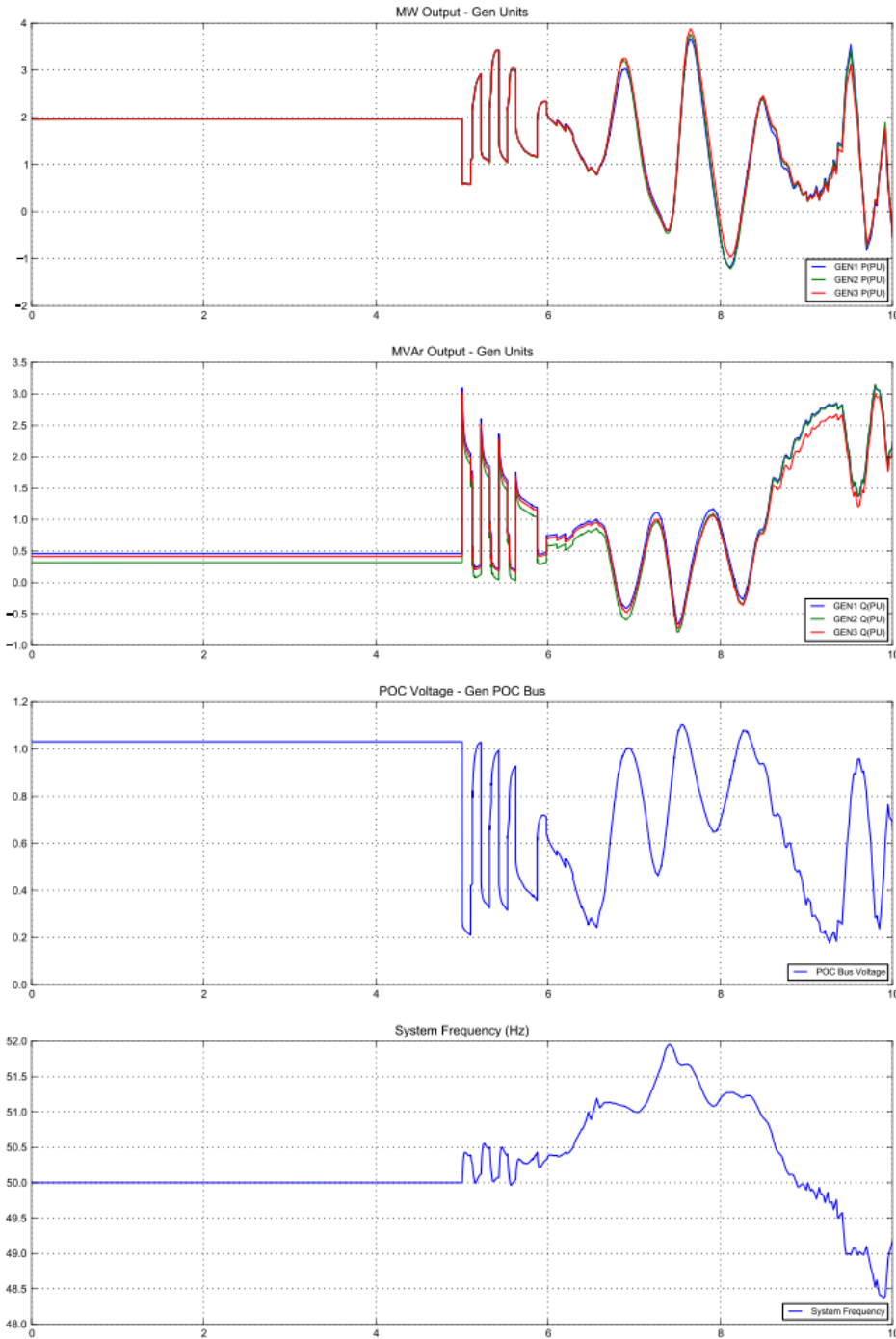
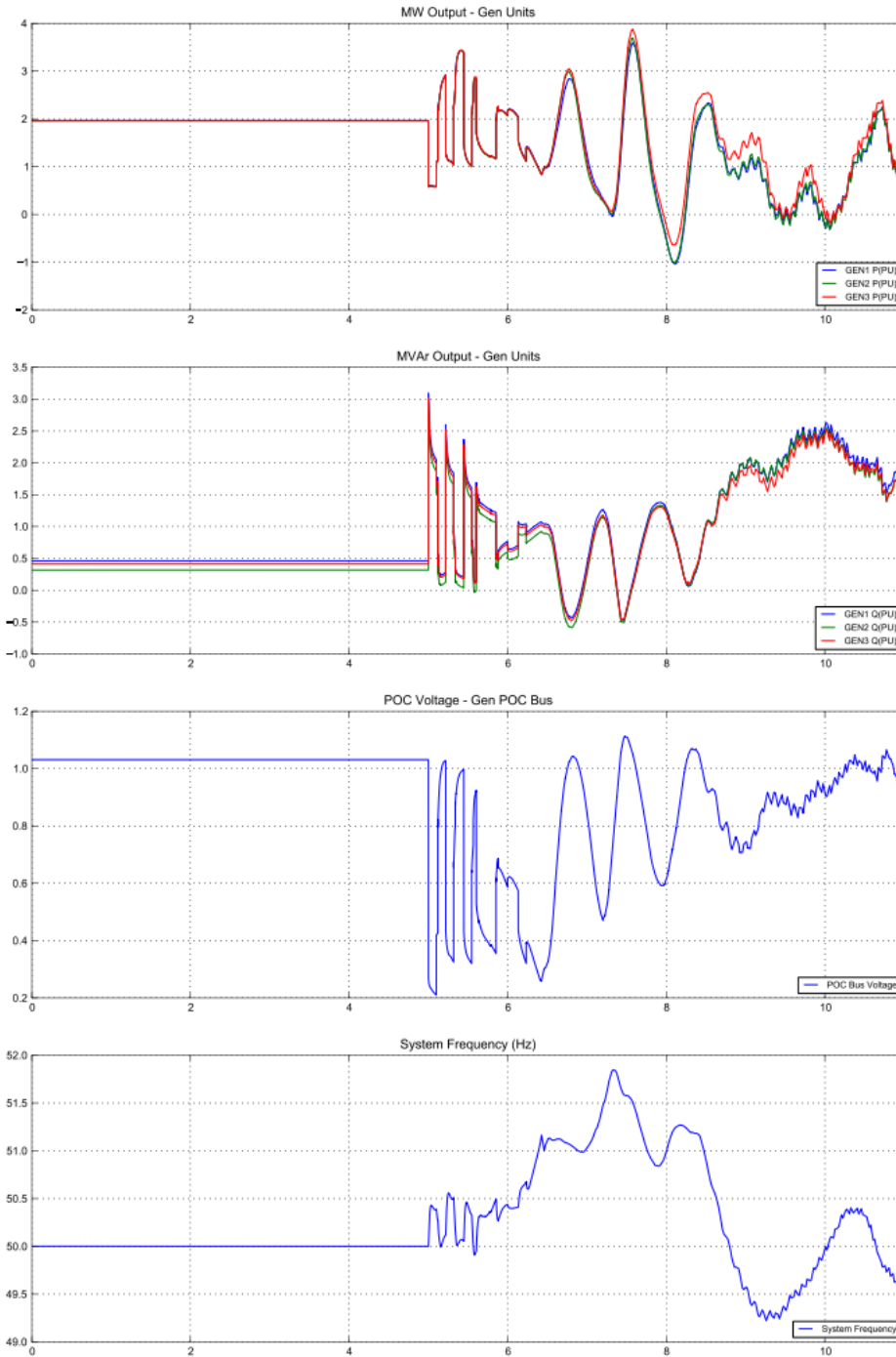




Figure 23 Case 1b-3 Synchronous Generating System 1 unstable Case 3

Simulation Time:20180125\_165403,Simulation Title:Sync Generator in highly interconnected transmission network  
dV x dT = 0.50514411456, POC voltage below 0.9pu for 1.224s





## APPENDIX B. CONTROL SYSTEM INTERACTION AND LOW VOLTAGE RIDE-THROUGH RE-TRIGGERING

Generation control systems that are not well tuned can result in voltage oscillations. Such an interaction may be triggered by a change in grid conditions, and voltage oscillations can occur if certain conditions are met.

One such phenomenon is the Low Voltage Ride-Through (LVRT) mode re-triggering in asynchronous generation, where a generating system is constantly switching operation modes between normal operation mode and LVRT mode.

In a Single Machine Infinite Bus (SMIB) type simulation, LVRT mode re-triggering is usually observed when the connection point voltage is reduced to a LVRT threshold level and is held constant at that level. Simulation examples of such performance are provided below.

In NEM-wide simulations, LVRT re-triggering can also usually be observed under specific power system and disturbance conditions.

While LVRT re-triggering is less likely to occur during system-wide simulations or real power system operation, it highlights underlying problems within the generation control system tuning. These problems are mostly due to improper selection of LVRT entry thresholds, lack of appropriate hysteresis, and/or aggressive reactive current contributions during a disturbance. Simulation results indicated that with proper tuning, this type of LVRT re-triggering can be eliminated.

When voltage oscillations are caused by the control system, such as LVRT re-triggering, they should not be considered when assessing performance against the proposed access standard for multiple-disturbance ride-through. The purpose of the proposed access standard is for generating systems to ride through multiple disturbances and the subsequent connection point voltage profile, where the voltage profile is imposed on the generating system due to actual power system disturbances (for example, faults), rather than voltage profiles created by the control system, especially when it is not properly tuned.

It is also noted in simulation that when LVRT re-triggering occurs, the generating system connection point voltage is always below 0.9 pu, effectively behaving similarly to failed voltage recovery, rather than acting like a multiple-disturbance occurrence. Such a phenomenon is not relevant to multiple disturbance ride-through capability assessment, and should be addressed as part of the controller tuning process. This is because such a response can be eliminated by judicious design of control systems, and as such, controllable compared to natural power system disturbances.

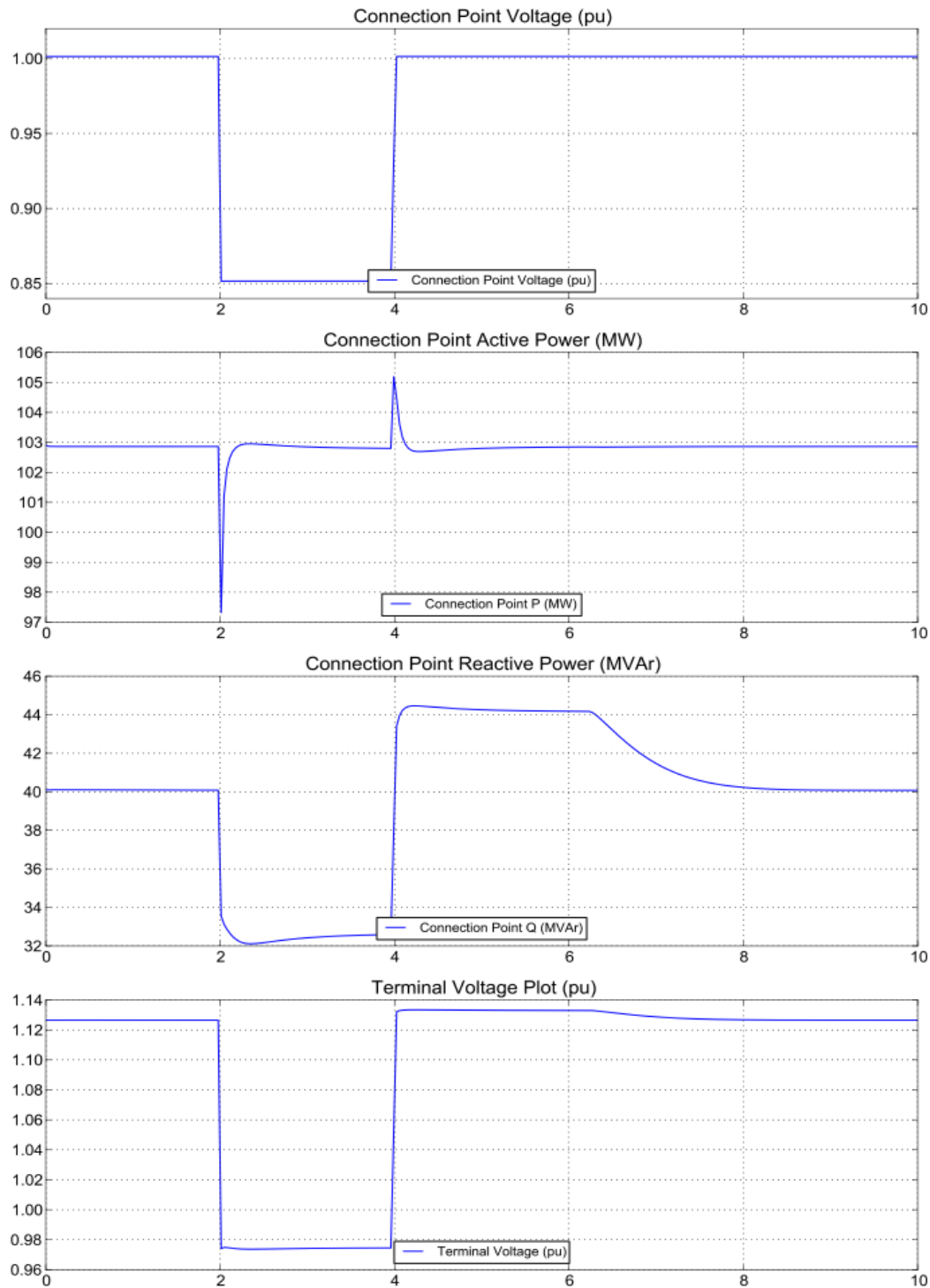
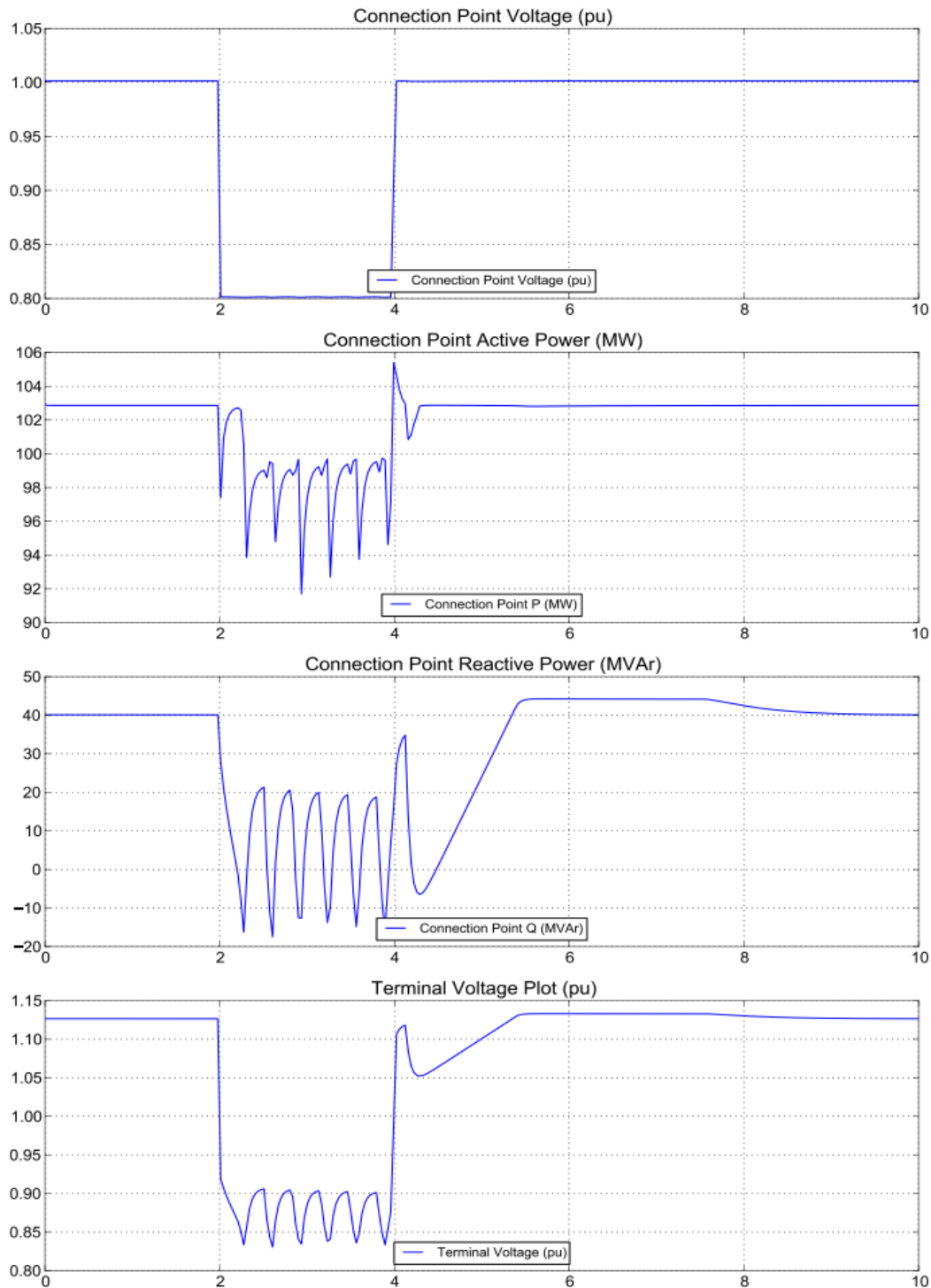
**Figure 24 Connection point voltage drops to 85%, no LVRT re-triggering**





Figure 25 Connection point voltage drops to 80%, LVRT re-triggering



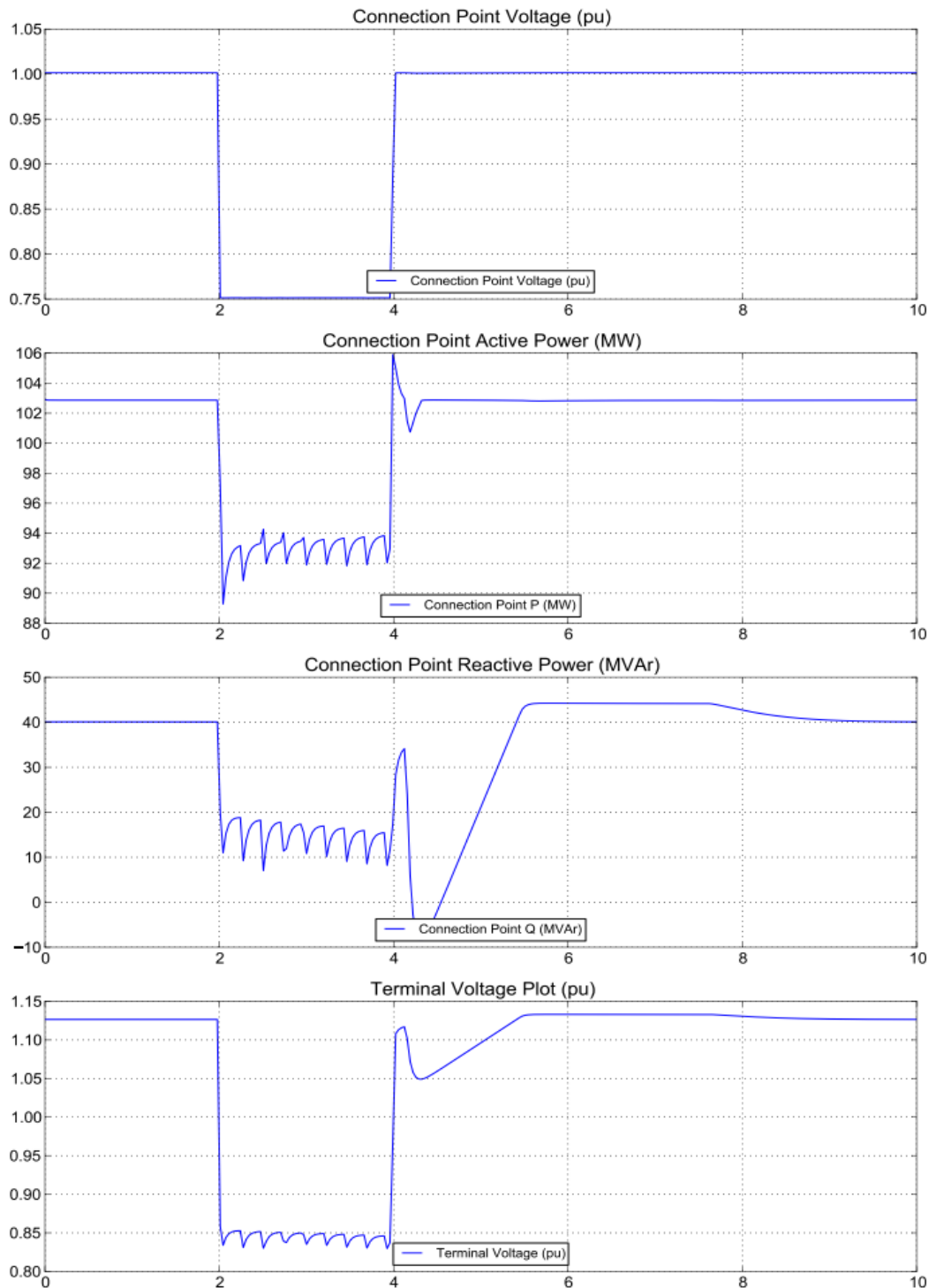
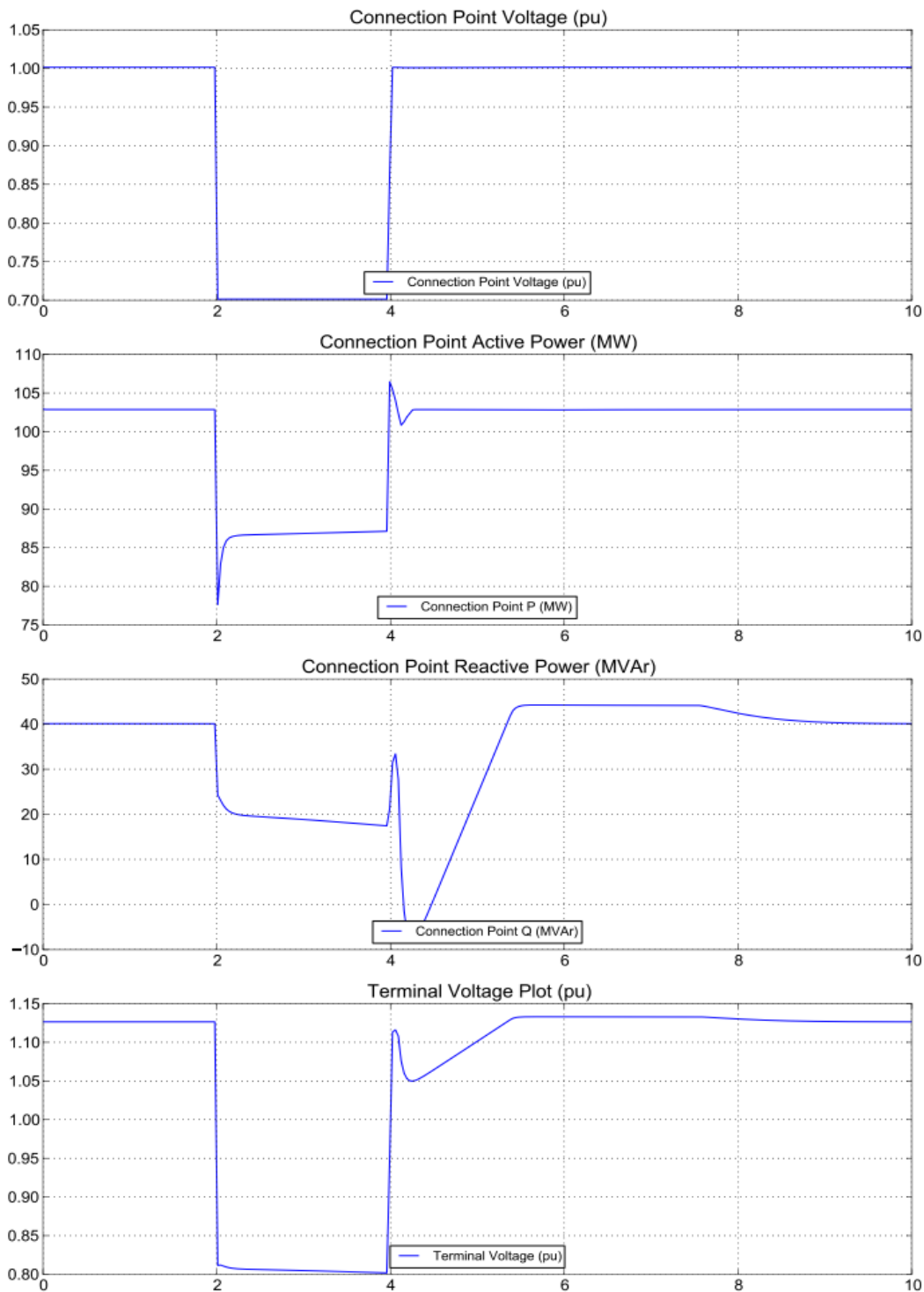
**Figure 26 Connection point voltage drops to 75%, LVRT re-triggering**



Figure 27 Connection point voltage drops to 70%, no LVRT re-triggering

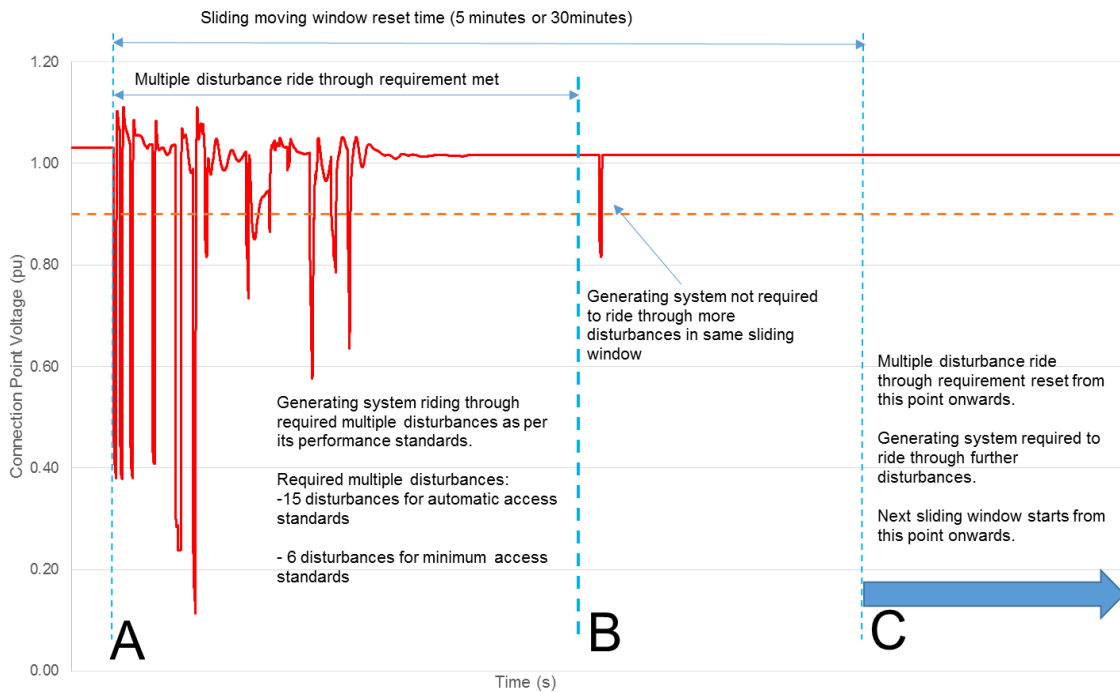


# APPENDIX C. DETAILED DEFINITIONS

## C.1 Sliding window reset time

The concept of the sliding window, and the requirement to ride through multiple disturbances within a sliding window, is illustrated in the following chart:

**Figure 28 Concept of sliding window**



In Figure 28, a sliding window is defined as the time between Point A and C, where Point A starts immediately when the first disturbance occurs. The size of the sliding window might vary between 5 minutes and 30 minutes for different generating systems, and a value within this range must be determined in the generating system’s performance standards.

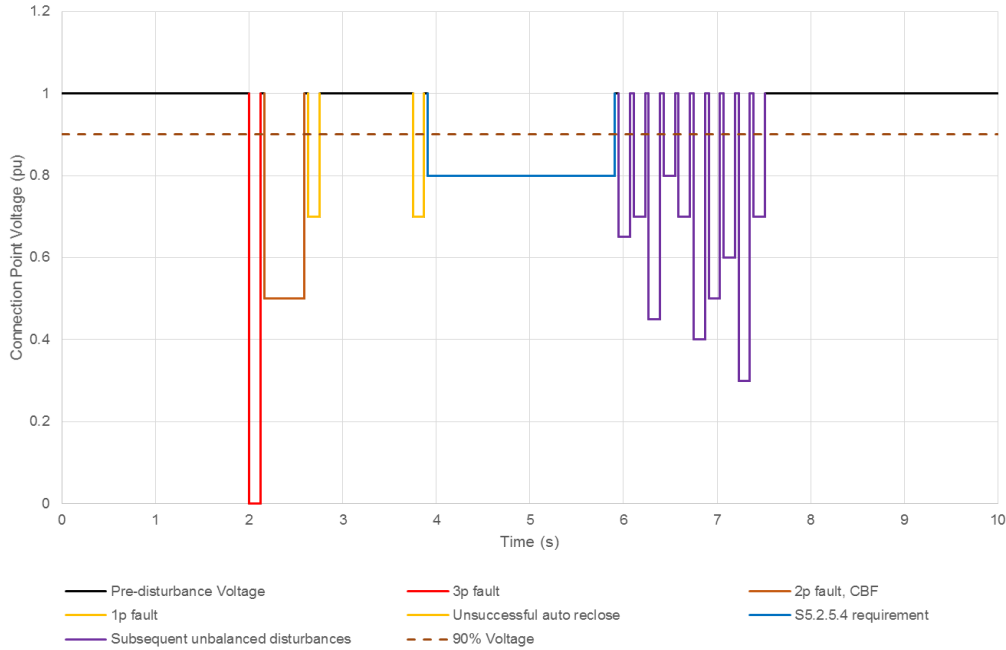
In Figure 28, the generating system has met the multiple-disturbance ride-through requirement between Point A and B. Hence, it is not required to ride through any disturbance between Point B and C, where such a disturbance would cause the connection point voltage to exceed +/-10% of its nominal voltage.

The sliding window is reset immediately from Point C onwards. All multiple-disturbance ride-through requirements are reset, and the generating system will need to ride through further disturbances in the new sliding window until these requirements are met.

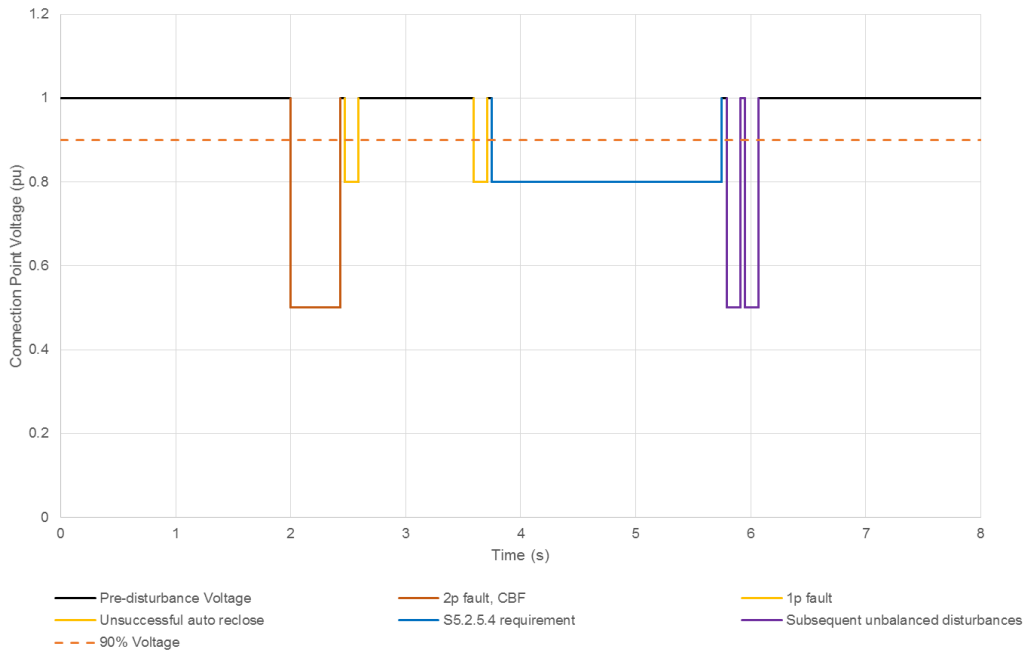
## C.2 Considered disturbances

Only disturbances in the “Types of disturbances to be considered” are to be included in the assessment for multiple-disturbance ride-through requirement. Examples of disturbances sequence for the proposed automatic and minimum access standards are illustrated in the following figures.

**Figure 29 Example of disturbance sequence for the proposed automatic access standard**



**Figure 30 Example of disturbance sequence for the proposed minimum access standard**

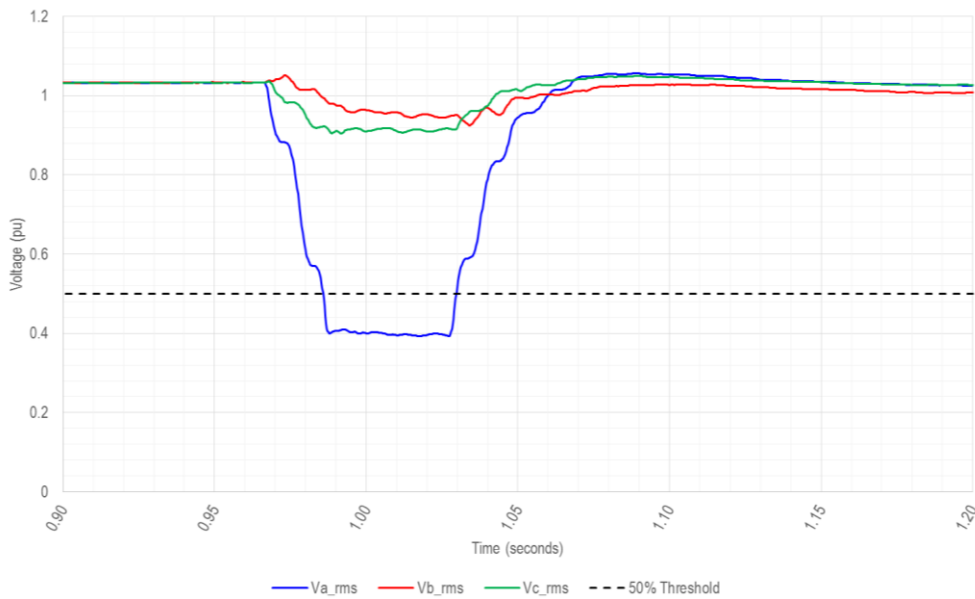


### C.3 Deep disturbance (fault) threshold

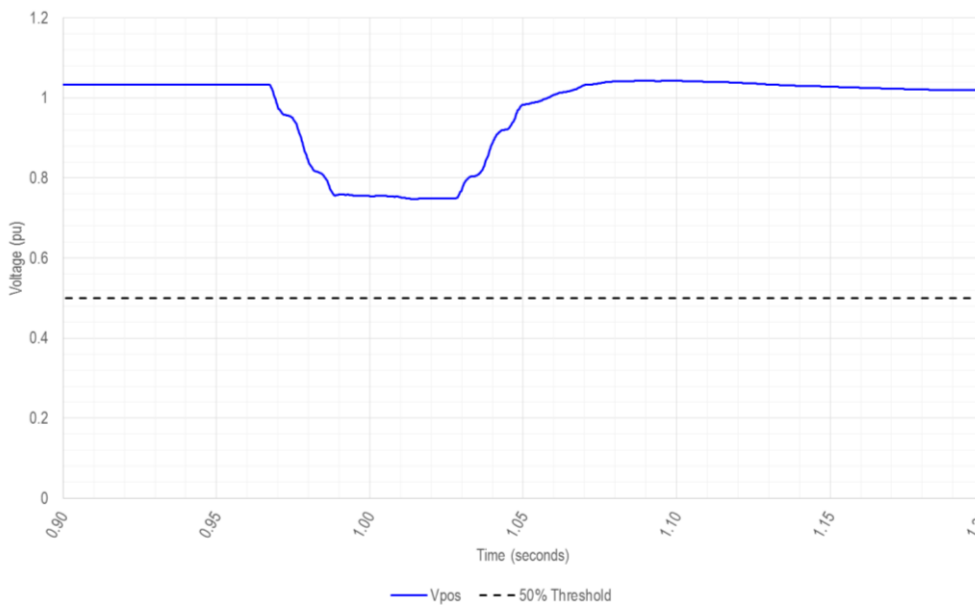
As defined in Table 3, the delineation between a shallow and deep fault is proposed to be 50% of the connection point voltage, where any voltage below 50% is considered to be a deep fault.

However, the voltage that initiates fault ride-through can be measured in different ways (primarily per phase RMS and positive sequence), and is often design-dependent. Figure 31 and Figure 32 show two different voltage measurement methods for the same fault, resulting in different outcomes as to whether the fault is considered deep (residual voltage < 50%) or shallow (residual voltage > 50%). Generally, fault ride-through mechanisms will use the lowest of the three-phase voltages. When a design has been demonstrated to use the positive-sequence voltage for initiating the ride-through sequence, however, the positive sequence voltage will be used for assessing the number of deep voltage disturbances.

**Figure 31 Fault voltage – Phase RMS voltage**

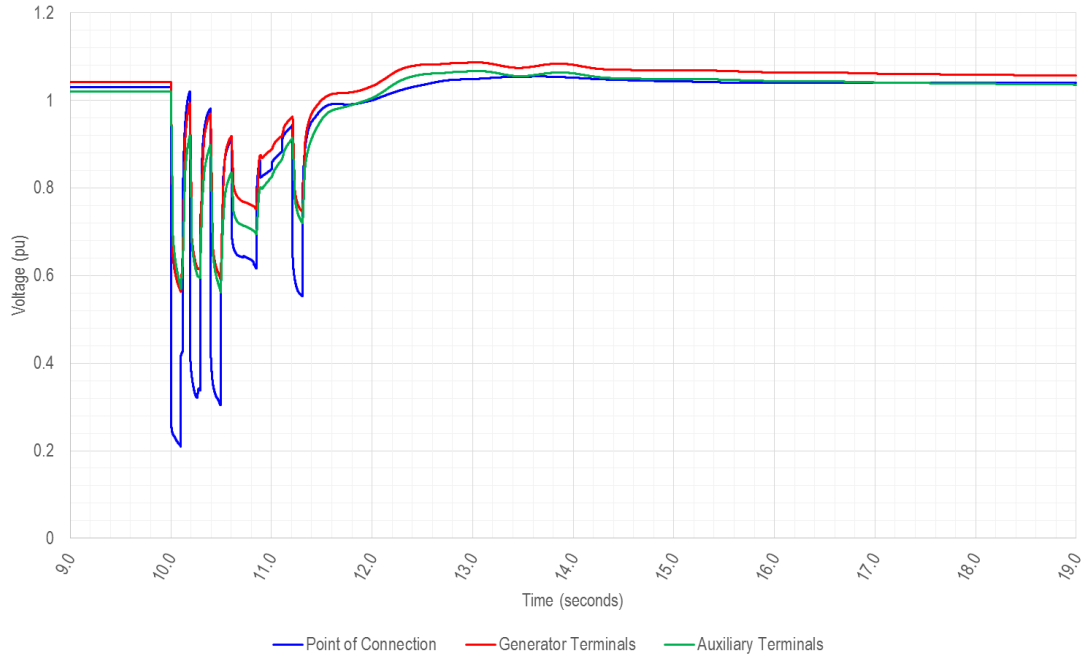


**Figure 32 Fault voltage – Positive sequence voltage**

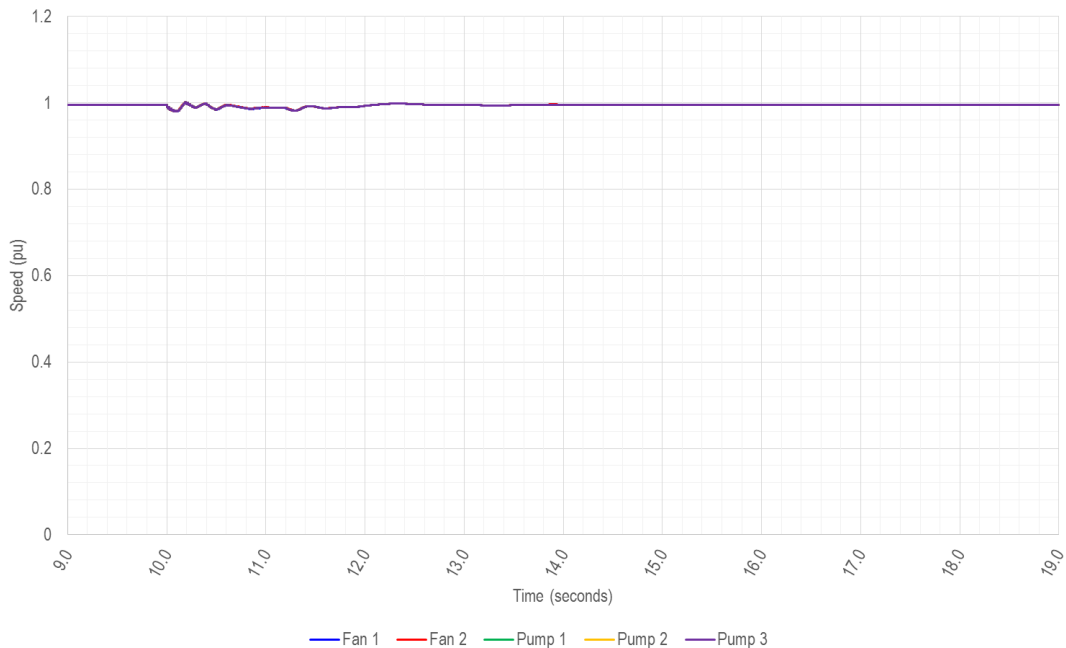


# APPENDIX D. PSCAD™/EMTDC™ SIMULATION RESULTS FOR SYNCHRONOUS GENERATING UNITS AUXILIARY SUPPLIES

**Figure 33** Auxiliary supplies terminal voltages



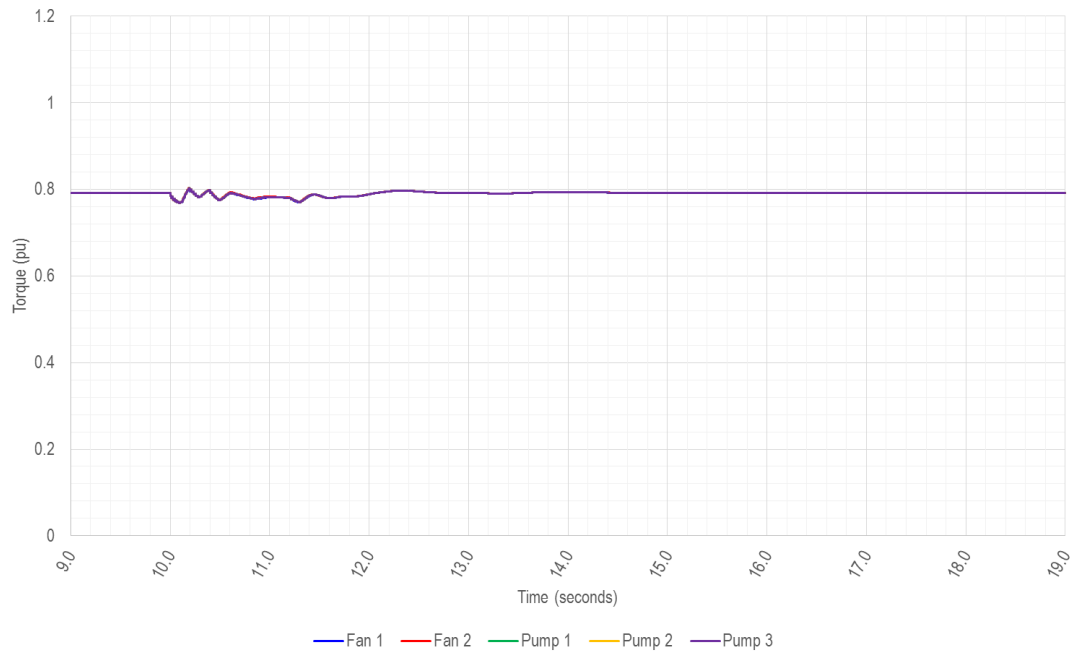
**Figure 34** Auxiliary supplies performance – motor speed





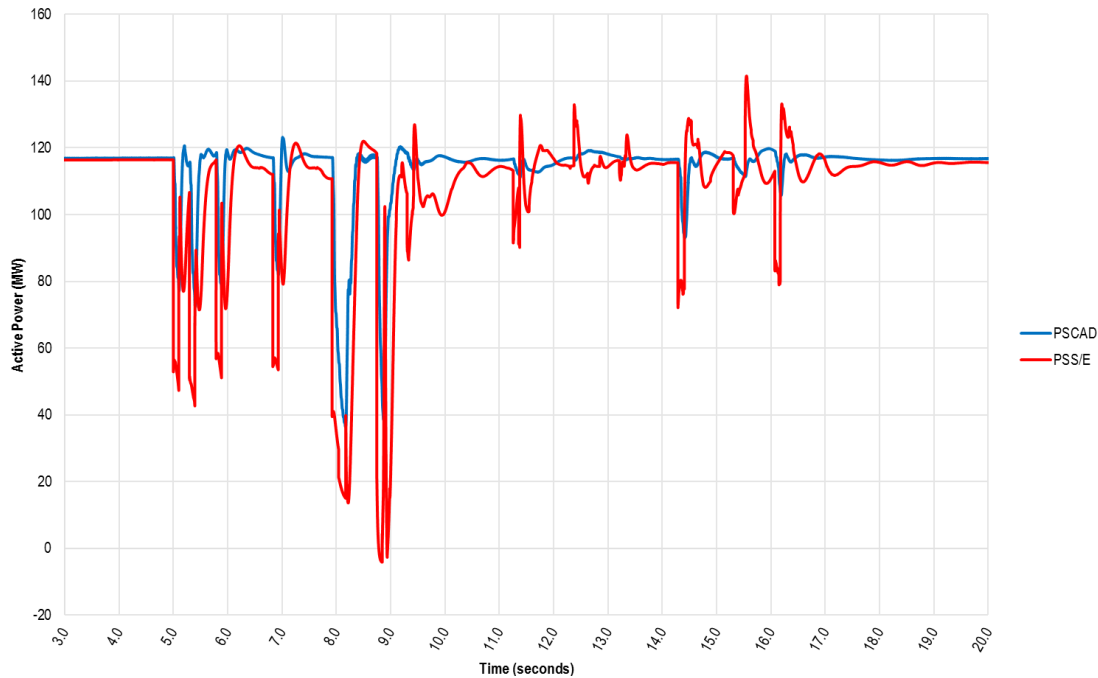


**Figure 35 Auxiliary supplies performance – motor torque**



# APPENDIX E. COMPARISON OF PSCAD™/EMTDC™ AND PSS®E MODEL PERFORMANCE FOR MULTIPLE DISTURBANCE RIDE THROUGH

**Figure 36** Wind farm active power comparison between PSCAD™/EMTDC™ and PSS®E models



**Figure 37** Wind farm reactive power comparison between PSCAD™/EMTDC™ and PSS®E models

